TEXAS INSTRUMENTS

UCC28881

ZHCSEL3B −NOVEMBER 2015−REVISED JANUARY 2016

UCC28881 700V、225mA 低静态电流离线转换器

1 特性

- 集成 14Ω、700V 功率金属氧化物半导体场效应晶体管 (MOSFET)
- 集成高电压电流源，用于内置器件偏置电源
- 集成电流感测
- 内部软启动
- 自偏置开关（直接在经整流的市电电压下启动和运行）
- 支持降压、降压/升压和反激拓扑结构
- 器件静态电流 <100µA
- 在负载电路短路期间提供稳定的电流保护
- 保护
  - 电流限制保护
  - 过载和输出短路保护
  - 过热保护

2 应用

- AC-DC 电源
  （非隔离式降压转换器，其在连续导通模式 (CCM) 和断续导通模式 (DCM) 下的
  输出电流分别高达 225mA 和 150mA）
- 电表、家庭自动化开关模式电源 (SMPS)
- 支持微控制器 (MCU)、射频 (RF) 和物联网 (IoT) 的设备的偏置电源
- 家用电器、大型家用电器和发光二极管 (LED) 驱动器
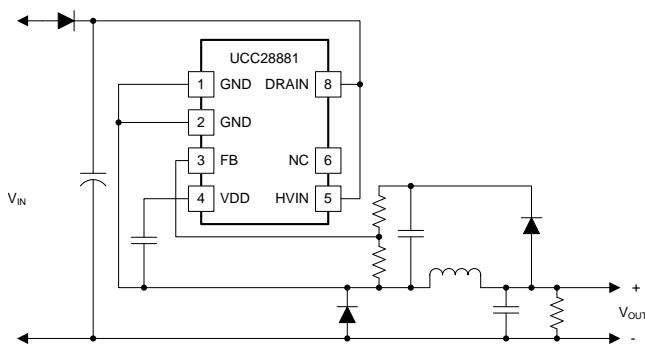
3 说明

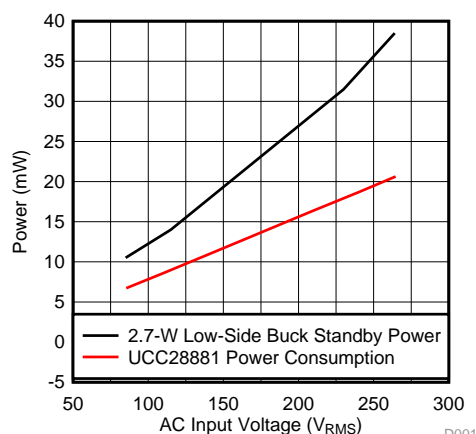UCC28881 在单片器件中集成了控制器和 14Ω、700V 功率 MOSFET。该器件还集成了高电压电流源，能够在经整流的市电电压下直接启动和运行。UCC28881 与 UCC28880 属于同一器件系列，具备高电流处理能力。

该器件的静态电流较低，能够提供出色的效率。凭借 UCC28881，使用最少的外部组件即可构建降压、降压/升压以及反激拓扑等最常用的转换器拓扑。

UCC28881 集成了控制功率级启动的软启动功能，能够最大程度地减小功率级组件所受的压力。

器件信息[1]

部件号	封装	封装尺寸（标称值）
UCC28881	SOIC (7)	5.00mm x 6.20mm

(1) 要了解所有可用封装，请见数据表末尾的可订购产品附录。

简化电路原理图

目录

4   修订历史记录

Changes from Revision A (December 2015) to Revision B   **Page**

• 已更改 文档标题"UCC28881 700V、225mA 低静态电流离线开关"至"UCC28881 700V、225mA 低静态电流离线转换器"。 1

Changes from Original (November 2015) to Revision A   **Page**

• 已更改 销售状态"产品预览"至"量产数据"。 1

5 Device Comparison

Power Handling Capability with Different Topologies

PRODUCT	MAXIMUM OUTPUT CURRENT for 85 ~ 265 VAC OPEN FRAME DESIGN	MAXIMUM OUTPUT POWER for 85 ~ 265 VAC OPEN FRAME DESIGN
	NON-ISOLATED BUCK	FLYBACK
UCC28880	100 mA	3 W
UCC28881	225 mA	4.5 W

6 Pin Configuration and Functions

D package
8-Pin SOIC
Top View

```
        ┌─────────────┐
GND ──1 │             │ 8── DRAIN
GND ──2 │             │
 FB ──3 │             │ 6── NC
VDD ──4 │             │ 5── HVIN
        └─────────────┘
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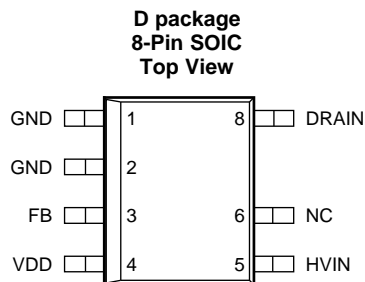
Pin Functions

PIN NAME	NO.	I/O	DESCRIPTION
DRAIN	8	P	Drain pin
FB	3	I	Feedback terminal
GND	1	G	Ground
GND	2	G	Ground
HVIN	5	P	Supply pin
NC	6	N/C	Not internally connected
VDD	4	O	Supply pin, supply is provided by internal LDO

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) [1] [2] [3]

		MIN	MAX	UNIT
HVIN		−0.3	700 [4]	V
DRAIN		Internally clamped	700 [4]	V
I_{DRAIN}	Positive drain current single pulse, pulse max duration 25 μs		770 [5]	mA
I_{DRAIN}	Negative drain current	−700		mA
FB		−0.3	6	V
VDD	VDD is supplied from low impedance source	−0.3	6	V
I_{VDD}	VDD is supplied from high impedance source		400	μA
T_J	Junction temperature		150	°C
	Lead temperature 1.6 mm (1/16 inch) from case 10 seconds		260	°C
T_{stg}	Storage temperature range	−65	150	°C

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltages are with respect to GND. Currents are positive into, negative out of the specified terminal. These ratings apply over the operating ambient temperature ranges unless otherwise noted.
(3) The device is not rated to withstand operating conditions when multiple parameters are at or near, absolute maximum ratings.
(4) T_A = 25°C
(5) The MOSFET drain to source voltage is less than 400V

7.2 ESD Ratings

			UNIT
$V_{(ESD)}$ Electrostatic discharge	Human Body Model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins except HVIN pin [1]	±2000	V
	Human Body Model (HBM) per ANSI/ESDA/JEDEC JS-001, HVIN pin [1]	±1500	V
	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins [2]	±500	V

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V_{VDD}	Voltage On VDD pin		5		V
V_{FB}	Voltage on FB pin	–0.2		5	V
T_J	Operating junction temperature	–40		+125	°C

7.4 Thermal Information

THERMAL METRIC [1]		UCC28881 D (SOIC) 7 PINS	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	134.4	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	42.6	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	85	°C/W
ψ_{JT}	Junction-to-top characterization parameter	6.4	°C/W
ψ_{JB}	Junction-to-board characterization parameter	76	°C/W

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, SPRA953.

7.5 Electrical Characteristics

V_{HVIN} = 30 V, T_A = T_J = –40°C to +125°C (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{HVIN(min)}$	Minimum Voltage to start-up				30	V
I_{NL}	Internal supply current, no load	FB = 1.25 V (> V_{FB_TH})		58	100	μA
I_{FL}	Internal supply current, full load	FB = 0.75 V (> V_{FB_TH})		86	120	μA
I_{CH0}	Charging VDD Cap current	V_{VDD} = 0 V,	–3.8	–1.6	–0.4	mA
I_{CH1}	Charging VDD Cap current	V_{VDD} = 4.4V, V_{FB} = 1.25 V	–3.40	–1.30	–0.25	mA
V_{VDD}	Internally regulated low Voltage supply (supplied from HVIN pin)		4.5	5.0	5.5	V
V_{FB_TH}	FB pin reference threshold		0.96	1.03	1.105	V
$V_{VDD(on)}$	VDD turn-on threshold	VDD low-to-high	3.55	3.92	4.28	V
$V_{VDD(off)}$	VDD turn-off threshold	VDD high-to-low	3.28	3.62	3.89	V
$\Delta V_{VDD(uvlo)}$	VDD UVLO Hysteresis	VDD high-to-low	0.27	0.345	0.39	V
D_{MAX}	Maximum Duty Cycle	FB = 0.75 V	45%		55%	
I_{LIMIT}	Current Limit	Static, T_A = –40°C			630	mA
		Static, T_A = 25°C	330	440	570	mA
		Static, T_A = 125°C	315			mA
$T_{J(stop)}$	Thermal Shutdown Temperature	Internal junction temperature		138.5	150	°C
$T_{J(hyst)}$	Thermal Shutdown Hysteresis	Internal junction temperature		37.	45	°C
BV	Power MOSFET Breakdown Voltage	T_J = 25°C	700			V
$R_{DS(on)}$	Power MOSFET On-Resistance (includes internal sense-resistor)	I_D = 60 mA, T_J = 25°C		14	18	Ω
		I_D = 60 mA, T_J = 125°C		24	30	Ω
DRAIN_$I_{LEAKAGE}$	Power MOSFET off state leakage current	V_{DRAIN} = 700V, T_J = 25°C			5	μA
		V_{DRAIN} = 400 V, T_J = 125°C			20	μA
HVIN_I_{OFF}	HVIN off state current	V_{HVIN} = 700 V, T_J = 25°C, V_{VDD} = 5.8 V	4.0	7.5	36.0	μA
		V_{HVIN} = 400 V, T_J = 125°C, V_{VDD} = 5.8 V			20	μA
$V_{VDD(clamp)}$	VDD clamp voltage	I_{VDD} = 250 μA	6.0	6.7	7.5	V

7.6 Switching Characteristics

over operating free-air temperature range (unless otherwise noted)

		MIN	TYP	MAX	UNIT
$f_{SW(max)}$	Maximum switching frequency	52	62	75	kHz
t_{ON_MAX}	Maximum switch on time (current limiter not triggered), FB = 0.75 V	6.5	8.3	9.7	μs
t_{OFF_MIN}	Minimum switch off time follows every t_{ON} time, FB = 0.75 V	6.5	8.3	9.7	μs
t_{MIN}	Minimum on time	0.17	0.27	0.30	μs
$t_{OFF(ovl)}$	Max off time (OL condition), $t_{OFF(ovl)}$ = t_{SW} − $t_{ON(max)}$	130	200	270	μs
t_{ON_TO}	Inductor current run away protection time threshold		450		ns

Typical Characteristics (continued)
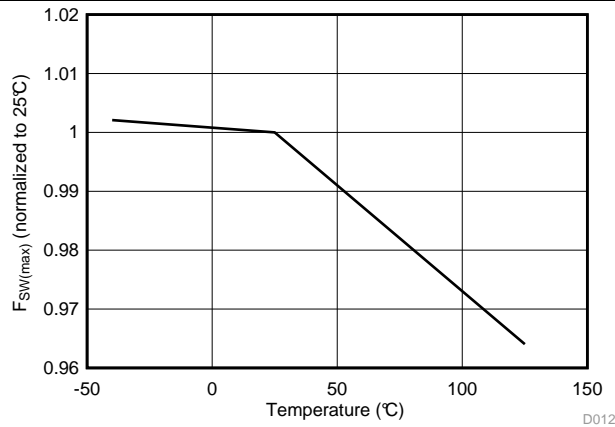

Figure 7. Maximum Switching Frequency vs Temperature
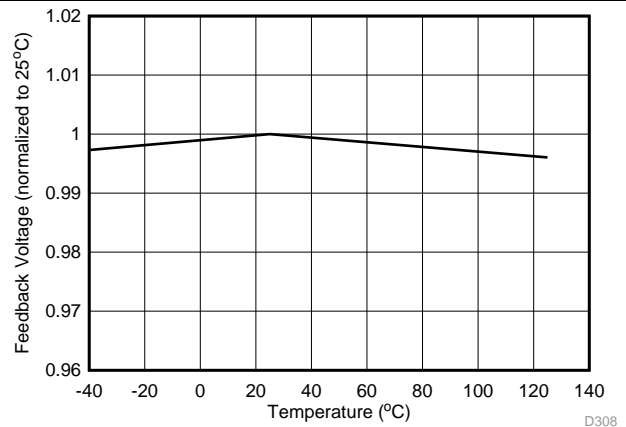

Figure 8. V_{FB_TH} vs Temperature
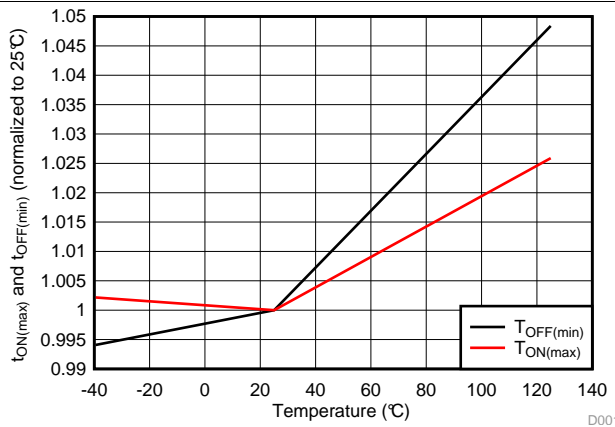

Figure 9. t_{ON(max)} and t_{OFF(min)} vs Temperature
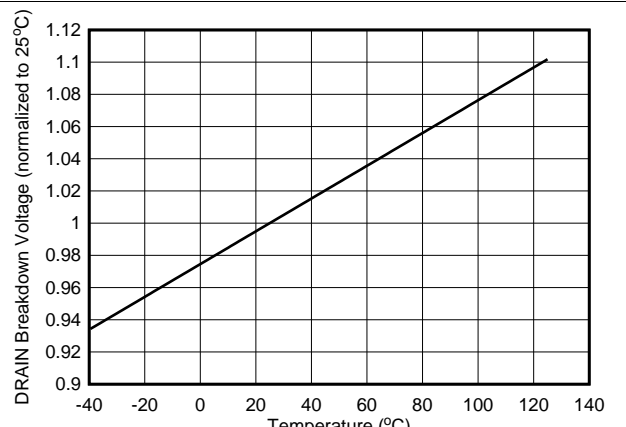

Figure 10. DRAIN breakdown voltage vs Temperature
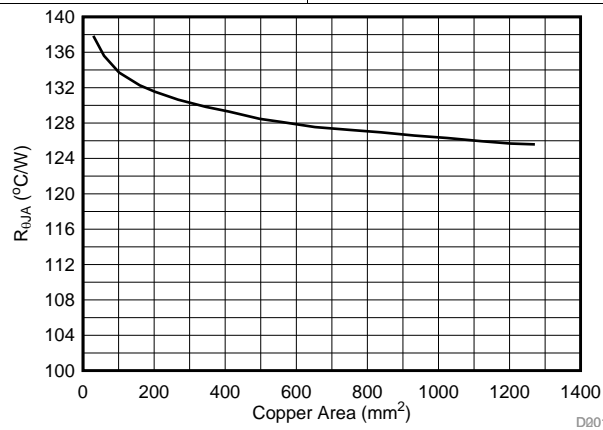

Figure 11. R_{TH}J_A vs Copper Area

8 Detailed Description

8.1 Overview

The UCC28881 integrates a controller and a 700-V power MOSFET into one monolithic device. The device also integrates a high-voltage current source, enabling start up and operation directly from the rectified mains voltage. UCC28881 is the same family device as UCC28880 and it provides higher power handling capability.

The low-quiescent current of the device enables excellent efficiency. The device is suitable for non-isolated AC-to-DC low-side buck and buck-boost configurations with level-shifted direct feedback, but also more traditional high-side buck, buck boost and low-power flyback converters with low standby power can be built using a minimum number of external components.

The device generates its own internal low-voltage supply (5 V referenced to the device's ground, GND) from the integrated high-voltage current source. The PWM signal generation is based on a maximum constant on-time, minimum off-time concept, with the triggering of the on-pulse depending on the feedback voltage level. Each on-pulse is followed by a minimum off-time to ensure that the power MOSFET is not continuously driven in an on-state. The PWM signal is AND-gated with the signal from a current limit circuit. No internal clock is required, as the switching of the power MOSFET is load dependent. A special protection mechanism is included to avoid runaway of the inductor current when the converter operates with the output shorted or in other abnormal conditions that can lead to an uncontrolled increase of the inductor current. This special protection feature keeps the MOSFET current at a safe operating level. The device is also protected from other fault conditions with thermal shutdown, under-voltage lockout and soft-start features.

8.2 Functional Block Diagram
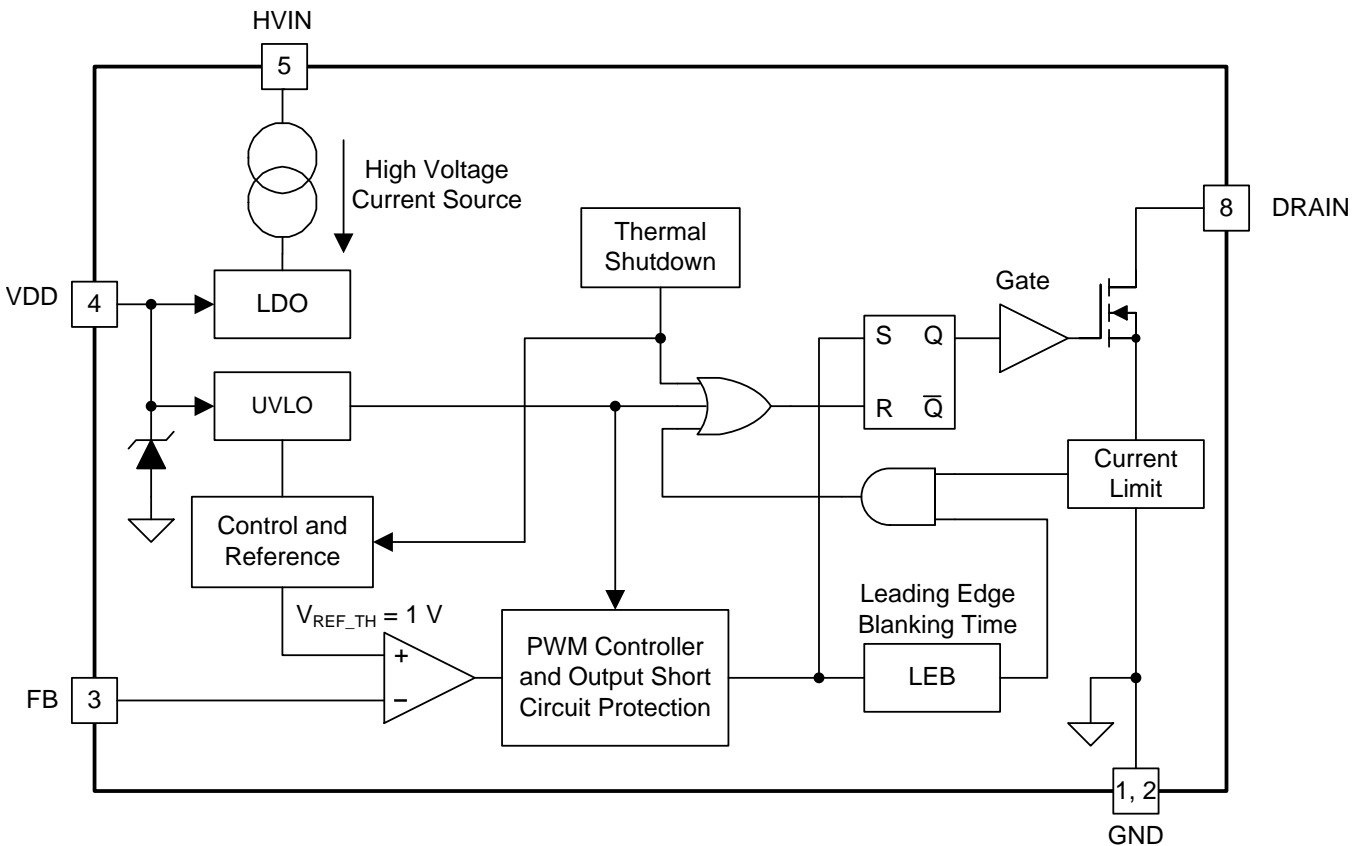
8.3 Feature Description

The UCC28881 integrates a 700-V rated power MOSFET switch, a PWM controller, a high-voltage current source to supply a low-voltage power supply regulator. A bias and reference block, thermal shutdown and the following protection features, current limiter, under voltage lockout (UVLO) and overload protection for situations like short circuit at the output are also integrated inside UCC28881. UCC28881 is the same family device as UCC28880 and it provides higher power handling capability.

The positive high-voltage input of the converter node (VIN+) functions as a system reference ground for the output voltage in low-side topologies. In the low-side buck topology the output voltage is negative with respect to the positive high-voltage input (VIN+), and in low-side buck-boost topology the output voltage is positive with respect to the positive high-voltage input (VIN+).

In low-side buck and buck-boost topologies, the external level-shifted direct feedback circuit can be implemented by two resistors and a high-voltage PNP transistor.

In high-side buck configuration, as well as in non-isolated flyback configuration, the output voltage is positive with respect to the negative high-voltage input (VIN–), which is the system reference ground.

UCC28881 can operate under continuous conduction mode (CCM) or discontinuous conduction mode (DCM) mode. CCM operation allows the converter to deliver more output power because of less current ripple. However, it requires a higher inductor value and generally results in lower efficiency due to the added losses associated with diode reverse recovery current. DCM mode operation uses a smaller inductor and achieves better efficiency, but the output current handling capability is reduced because of increased current ripple. The table below shows the current handling capability in DCM and CCM operation for the UCC28880, UCC28881 family.

Table 1. Current Handling Capability for UCC28880 and UCC28881

DEVICE	CURRENT HANDLING MODE	230 V_{AC} ±15%	85 V ~ 265 V_{AC}
UCC28881	Discontinuous Conduction Mode (DCM)	150 mA	150 mA
UCC28881	Continuous Conduction Mode (CCM)	225 mA	225 mA
UCC28880	Discontinuous Conduction Mode (DCM)	70 mA	70 mA
UCC28880	Continuous Conduction Mode (CCM)	100 mA	100 mA

When the bus voltage is higher than 400 V, it is recommended to limit operation to DCM mode only to avoid the diode reverse recovery current and the associated internal MOSFET stress. Due to the higher switching loss and device stresses at higher bus voltage, it is recommended to keep the converter input voltage less than 560 V for the buck applications.

UCC28881 power handling capability is reduced at higher ambient temperature, as a function of the power dissipation of the device, the device's recommended maximum operating junction temperature and the thermal dissipation capability of the total system. De-rating of the output current according to maximum ambient temperature can be estimated from Figure 12. The de-rating estimation assumes CCM operation, 10 µJ of switching loss and 135°C/W $R_{\theta JA}$ and 30-kHz, full-load switching frequency. This is a conservative estimation. The thermal handling capability can be more accurately determined through experimental measurement. For more information on thermal evaluation methods see the IC Package and Thermal Metrics application report: SPRA953.
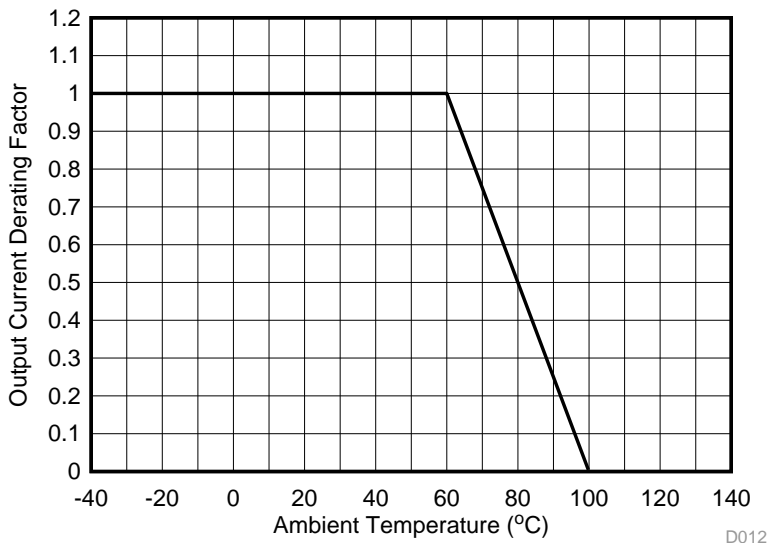
Figure 12. Output Current (De-Rating Factor) vs. Temperature

It is required to use fast recovery diode for the buck freewheeling diode. When designed in CCM, the diode reverse recovery time should be less than 35 ns to keep low reverse recovery current and the switching loss. For example, STTH1R06A provides 25-ns reverse recovery time. When designed in DCM, a slower diode can be used, but the reverse-recovery time should be kept less than 75 ns. MURS160 can fit the requirement.

The device has a low-standby power consumption (no-load condition), only 18 mW (typical) when connected to a 230-V_{AC} mains and 9 mW when connected to an 115-V_{AC} mains.

The standby power does not include the power dissipated in the external feedback path, the power dissipated in the external pre-load, the inductor in the freewheeling diode and the converter input stage (rectifiers and filter).

8.4 Device Functional Modes

8.4.1 Start-Up Operation

The device includes a high-voltage current source connected between the HVIN pin and the internal supply for the regulator. When the voltage on the HVIN pin rises, the current source is activated and starts to supply current to the internal 5-V regulator. The 5-V regulator charges the external capacitor connected between VDD pin and GND pin. When the VDD voltage exceeds the VDD turn-on threshold, $V_{VDD(on)}$, device starts operations. The minimum voltage across HVIN and GND pins, to ensure enough current to charge the capacitance on VDD pin, is $V_{HVIN(min)}$. At the First switching cycle the minimum MOSFET off time is set to be >100 µs and cycle-by-cycle is progressively reduced up to $t_{OFF(min)}$ providing soft start.

8.4.2 Feedback and Voltage Control Loop

The feedback circuit consists of a voltage comparator with the positive input connected to an internal reference voltage (referenced to GND) and the negative input connected to FB pin. When the feedback voltage at the FB pin is below the reference voltage V_{FB_TH} logic high is generated at the comparator output. This logic high triggers the PWM controller, which generates the PWM signal turning on the MOSFET. When the feedback voltage at the FB pin is above the reference voltage, it indicates that the output voltage of the converter is above the targeted output voltage set by the external feedback circuitry and PWM is stopped.

Device Functional Modes (continued)

8.4.3 PWM Controller

UCC28881 operates under on/off control. When the FB pin voltage is below internal reference 1 V, the converter is switching and sending power to the load. When the FB pin voltage is above internal reference 1 V, the converter shuts off and stops delivering power to the load.

The PWM controller does not need a clock signal. The PWM signal's frequency is set to $f_{SW(max)} = (1/(t_{ON(max)} + t_{OFF(min)}))$ which occurs when the voltage on the FB pin is continuously below V_{FB_TH}.

PWM duty cycle is determined by both the peak current and maximum on time. At each switching cycle, after turn on, the MOSFET is turned off if its current reaches the fixed peak-current threshold or its on time reaches the maximum value of on-time pulse $t_{ON(max)}$.

Normally the converter would operate under frequency control, which means the converter is only enabled one switching cycle and then disabled. Next switching cycle starts when output voltage decays and the feedback enable the converter again. This way, the converter appears to operate under variable switching frequency control.

The user might observe the converter operates in burst mode that converter is enabled for multiple switching cycles and then stopped for multiple switching cycles. This causes larger output voltage ripple. However, due to the infrequent switching it actually helps on the standby power at no load.
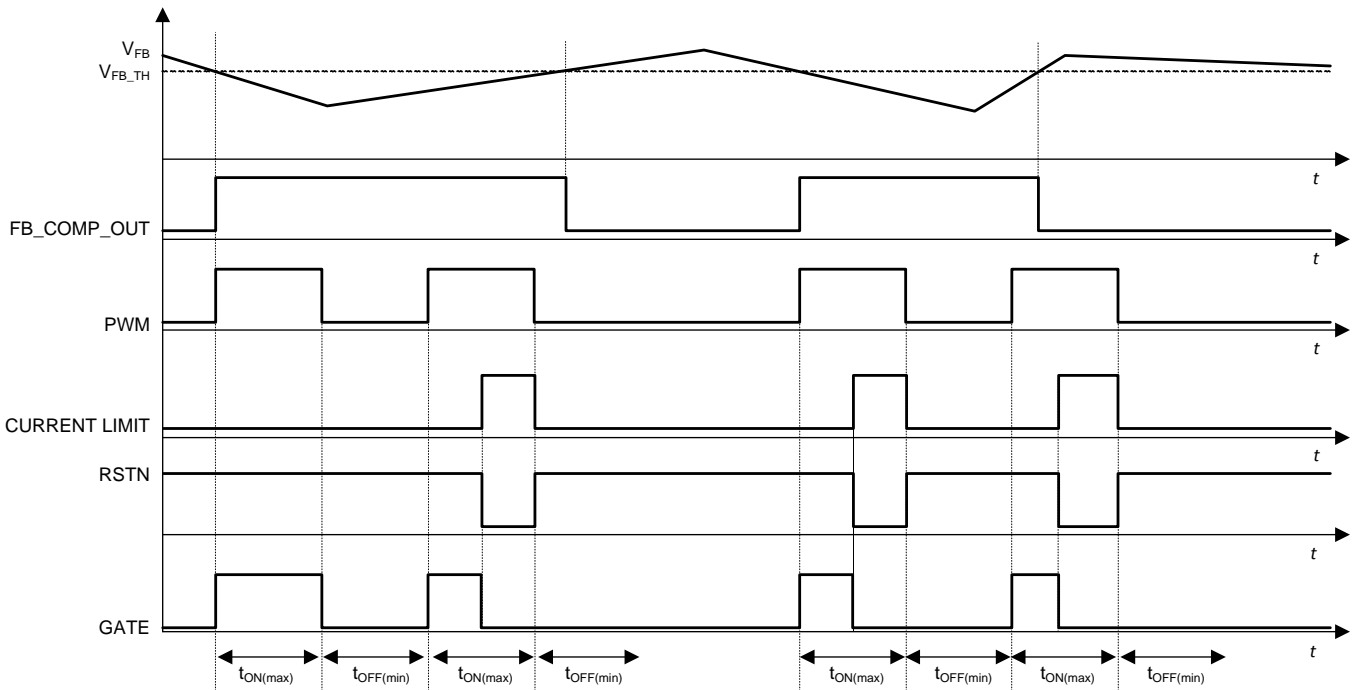

Figure 13. UCC28881 Timing Diagram

Device Functional Modes (continued)

8.4.4 Current Limit

The current limit circuit senses the current through the power MOSFET. The sensing circuit is located between the source of the power MOSFET and the GND pin. When the current in the power MOSFET exceeds the threshold I_{LIMIT}, the internal current limit signal goes high, which sets the internal RSTN signal low. This disables the power MOSFET by driving its gate low. The current limit signal is set back low after the falling edge of the PWM signal. After the rising edge of the GATE signal, there is a blanking time. During this blanking time, the current limit signal cannot go high. This blanking time and the internal propagation delay result in minimum on time, t_{MIN}.

8.4.5 Inductor Current Runaway Protection

To protect the device from overload conditions, including a short circuit at the output, the PWM controller incorporates a protection feature which prevents the inductor current from runaway. When the output is shorted the inductor demagnetization is very slow, with low di/dt, and when the next switching cycle starts energy stored in the inductance is still high. After the MOSFET switches on, the current starts to rise from pre-existing DC value and reaches the current-limit value in a short duration of time. Because of the intrinsic minimum on-time of the device the MOSFET on-time cannot be lower than t_{MIN}, in an overload or output short circuit the energy inductance is not discharged sufficiently during MOSFET off-time, it is possible to lose control of the current leading to a runaway of the inductor current. To avoid this, if the on-time is less than t_{ON_TO} (t_{ON_TO} is a device internal time out), the controller increases the MOSFET off-time (t_{OFF}). If the MOSFET on-time is longer than t_{ON_TO} then t_{OFF} is decreased. The controller increases t_{OFF}, cycle-by-cycle, through discrete steps until the on-time continues to stay below t_{ON_TO}. The t_{OFF} is increased up to $t_{OFF(ovl)}$ after that, if the on-time is still below t_{ON_TO} the off-time is kept equal to $t_{OFF(ovl)}$. The controller decreases t_{OFF} cycle-by-cycle until the on-time continues to stay above t_{ON_TO} up to $t_{OFF(min)}$. This mechanism prevents control loss of the inductor current and prevents over stress of the MOSFET (see typical waveforms in Figure 14 and Figure 15). At start up, the t_{OFF} is set to $t_{OFF(ovl)}$ and reduced cycle-by-cycle (if the on-time is longer than t_{ON_TO}) up to $t_{OFF(min)}$ providing a soft start for the power stage.
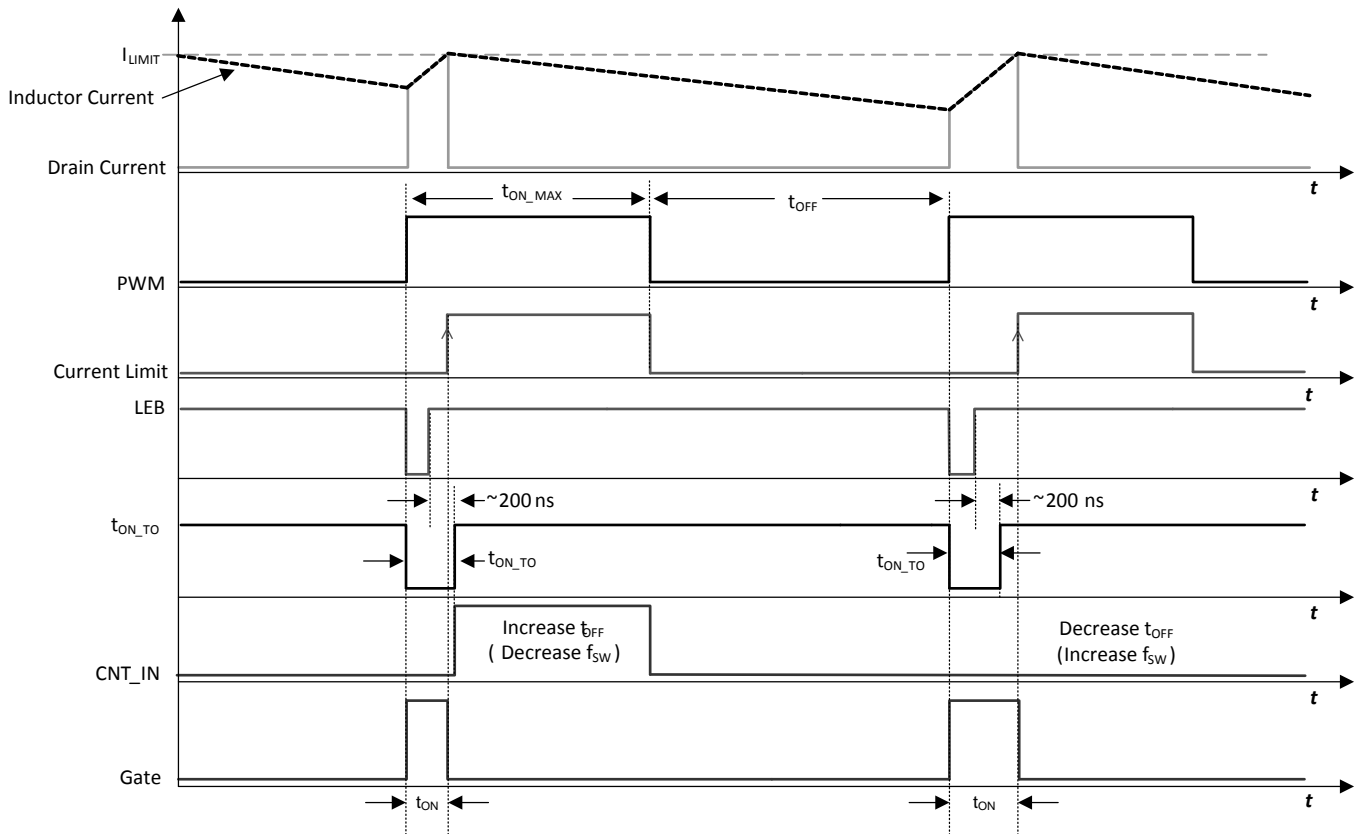

Figure 14. Current Runaway Protection Logic Timing Diagram
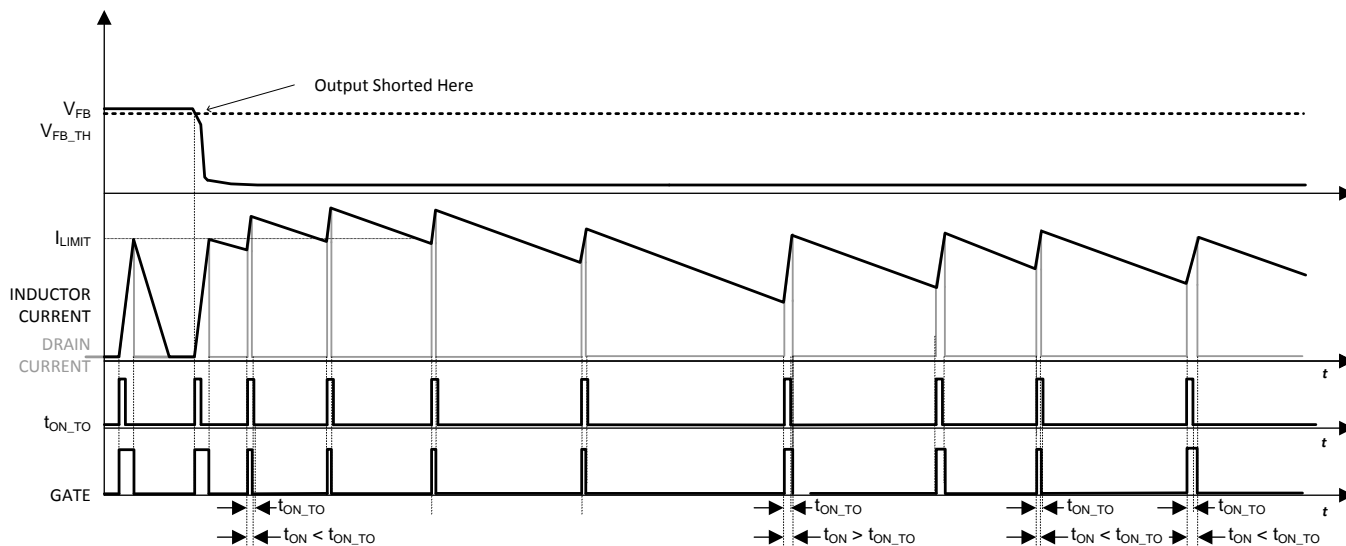
Device Functional Modes (continued)

Figure 15. Current Runaway Protection, Inductor and MOSFET Current

A minimal value needs to be imposed on the inductance value to avoid nuisance tripping of the protection feature that prevents the loss of control of the inductor current. Inadvertent operation of the protection feature limits the output-power capability of the converter. This condition depends on the converter's maximum input operating voltage and temperature. Use Equation 1 to calculate your minimum inductance value.

$$L > \frac{V_{IN(max)}}{I_{LIMIT}} \times t_{ON\_TO}$$

(1)

In this equation, $V_{IN(max)}$ is the maximum voltage on the DC input. If the input is a rectifed AC voltage, it should be the peak value of the maximum AC line. For a DC input case, it should be the maximum DC input voltage.

If the inductance value is too low, such that the MOSFET on-time is always less than t_{ON_TO} timeout and the device progressively increases the MOSFET off-time up to $t_{OFF(ovl)}$, the output power is reduced and the converter fails to supply the load.

8.4.6 Over Temperature Protection

If the junction temperature rises above $T_{J(stop)}$, the over temperature protection is triggered. This disables the power MOSFET switching. To re-enable the switching of the MOSFET the junction temperature has to fall by $T_{J(hyst)}$ below the $T_{J(stop)}$ where the device moves out of over temperature protection.

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The UCC28881 can be used in various application topologies with direct or isolated feedback. The device can be used in low-side buck, where the output voltage is negative, or as a low-side buck-boost configuration, where the output voltage is positive. In both configurations the common reference node is the positive input node (VIN+). The device can also be configured as a LED driver in either of the above mentioned configurations. If the application requires the AC-to-DC power supply output to be referenced to the negative input node (VIN–), the UCC28881 can also be configured as a traditional high-side buck as shown in Figure 16. In this configuration, the voltage feedback is sampling the output voltage VOUT, making the DC regulation less accurate and load dependent than in low-side buck configuration, where the feedback is always tracking the VOUT. However, high-conversion efficiency can still be obtained.

9.2 Typical Application

9.2.1 13-V, 225-mA High-Side Buck Converter

Figure 16 shows a typical application example of a non-isolated power supply, where the UCC28881 is connected in a high-side buck configuration having an output voltage that is positive with respect to the negative high-voltage input (VIN–). The output voltage is set to 13 V in this example, but can easily be changed by changing the value of R_{FB1}. This application can be used for a wide variety of household appliances and automation, or any other applications where mains isolation is not required.
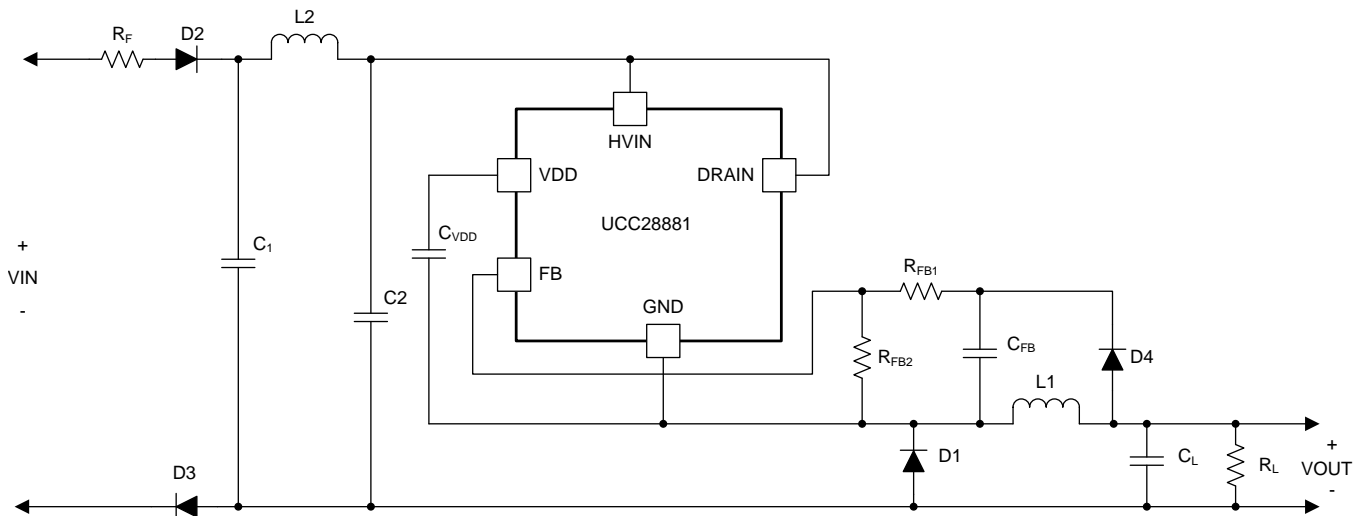

Figure 16. Universal Input, 12-V, 225-mA Output High-Side Buck

Typical Application (continued)

9.2.1.1 Design Requirements

Table 2. Design Specification

DESCRIPTION		MIN	TYP	MAX	UNIT
DESIGN INPUT					
V_{IN}	AC input voltage	85		265	V_{RMS}
f_{LINE}	Line frequency	47		63	Hz
I_{OUT}	Output current	0		225	mA
DESIGN REQUIREMENTS					
P_{NL}	No-load input power			500	mW
V_{OUT}	Output voltage	12.5	13	17.5	V
ΔV_{OUT}	Output voltage ripple			350	mV
η	Converter full-load efficiency	70%			

9.2.1.2 Detailed Design Procedure

9.2.1.2.1 Input Stage (R_F, D2, D3, C1, C2, L2)

- Resistor R_F is a flame-proof fusible resistor. R_F limits the inrush current, and also provide protection in case any component failure causes a short circuit. Value for its resistance is generally selected between 4.7 Ω to 15 Ω.
- A half-wave rectifier is chosen and implemented by diode D2 (1N4937). It is a general purpose 1-A, 600-V rated diode. It has a fast reverse recovery time (200 ns) for improved differential-mode-conducted EMI noise performance. Diode D3 (1N4007) is a general purpose 1-A, 1-kV rated diode with standard reverse recovery time (>500 ns), and is added for improved common-mode-conducted EMI noise performance. D3 can be removed and replaced by a short if not needed.
- EMI filtering is implemented by using a single differential-stage filter (C1-L2-C2).

Capacitors C1 and C2 in the EMI filter also acts as storage capacitors for the high-voltage input DC voltage (VIN). The required input capacitor size can be calculated according Equation 2.

$$C_{BULK(min)} = \frac{\dfrac{2 \times P_{IN}}{f_{LINE(min)}} \times \left[\dfrac{1}{RCT} - \dfrac{1}{2 \times \pi} \times \arccos\left(\dfrac{V_{BULK(min)}}{\sqrt{2} \times V_{IN(min)}} \right) \right]}{2 \times V_{IN(min)}^2 - V_{BULK(min)}^2}$$

where

- $C_{BULK(min)}$ is minimum value for the total input capacitor value (C1 + C2 in the schematic of Figure 16).
- RCT = 1 in case of half wave rectifier and RCT = 2 in case of full-wave rectifier .
- P_{IN} is the converter input power.
- $V_{IN(min)}$ is the minimum RMS value of the AC input voltage.
- $V_{BULK(min)}$ is the minimum allowed voltage value across bulk capacitor during converter operation.
- $f_{LINE(min)}$ is the minimum line frequency when the line voltage is $V_{IN(min)}$.

The converter input power can be easily calculated as follow:

- The converter maximum output power is: $P_{OUT} = I_{OUT} \times V_{OUT}$ = 0.225 A x 13 V = 2.925 W
- Assuming the efficiency η = 68% the input power is $P_{IN} = P_{OUT}/η$ = 4.178 W

Using the following values for the other parameters

- $V_{BULK(min)}$ = 80 V
- $V_{IN(min)}$ = 85 V_{RMS} (from design specification table)
- $f_{LINE(min)}$ = 57 Hz

(2)

$C_{BULK(min)}$ = 15.6 µF. Considering that electrolytic capacitors, generally used as bulk capacitor, have 20% of tolerance in value, the minimum nominal value required for C_{BULK} is:

$$C_{BULKn(min)} > \frac{C_{BULK(min)}}{(1 - TOL_{CBULK})} = 19.5\,\mu F$$

(3)

Select C1 and C2 to be 10 µF each (C_{BULK} = 10 µF + 10 µF = 20 µF > $C_{BULKn(min)}$).

By using a full-wave rectifier allows a smaller capacitor for C1 and C2, almost 50% smaller.

9.2.1.2.2 Regulator Capacitor (C_{VDD})

Capacitor C_{VDD} acts as the decoupling capacitor and storage capacitor for the internal regulator. A 100-nF, 10-V rated ceramic capacitor is enough for proper operation of the device's internal LDO.

9.2.1.2.3 Freewheeling Diode (D1)

The freewheeling diode has to be rated for high-voltage with as short as possible reverse-recovery time (t_{rr}).

The maximum reverse voltage that the diode should experience in the application, during normal operation, is given by Equation 4.

$$V_{D1(max)} = \sqrt{2} \times V_{IN(max)} = \sqrt{2} \times 265\,V = 375\,V$$

(4)

A margin of 20% is generally considered.

The use of a fast recovery diode is required for the buck-freewheeling rectifier. When designed in CCM, the diode reverse recovery time should be less than 35 ns to keep low reverse recovery current and the switching loss. For example, STTH1R06A provides 25-ns reverse recovery time. When designed in DCM, slower diode can be used, but the reverse recovery time should be kept less than 75 ns. MURS160 can fit the requirement.

9.2.1.2.4 Output Capacitor (C_L)

The value of the output capacitor impacts the output ripple. Depending on the combination of capacitor value and equivalent series resistor (R_{ESR}). A larger capacitor value also has an impact on the start-up time. For a typical application, the capacitor value can start from 47 µF, to hundreds of µF. A guide for sizing the capacitor value can be calculated by the following equations:

$$C_L > 20 \times \frac{I_{LIMIT} - I_{OUT}}{f_{SW(max)} \times \Delta V_{OUT}} = 20 \times \frac{440\,mA - 225\,mA}{62\,kHz \times 350\,mV} = 200\,\mu F$$

(5)

$$R_{ESR} < \frac{\Delta V_{OUT}}{I_{LIMIT}} = 0.8\,\Omega$$

(6)

Take into account that both C_L and R_{ESR} contribute to output voltage ripple. A first pass capacitance value can be selected and the contribution of C_L and R_{ESR} to the output voltage ripple can be evaluated. If the total ripple is too high the capacitance value has to increase or R_{ESR} value must be reduced. In the application example C_L was selected (330 µF) and it has an R_{ESR} of 0.03 Ω. So the R_{ESR} contributes for 4% of the total ripple. The formula that calculates C_L is based on the assumption that the converter operates in burst of twenty switching cycles. The number of bursts per cycle could be different, the formula for C_L is a first approximation.

9.2.1.2.5 Pre-Load Resistor (R_L)

The pre-load resistor connected at the output is required for the high-side buck topology. Unlike low side buck topology, the output voltage is directly sensed, in high-side buck topology the output is sampled and estimated. At no-load condition, because the feedback loop runs with its own time constant, the buck converter operates with a fixed minimum switching frequency. Select the pre-load resistor or using a zener diode to prevent output voltage goes too high at no-load condition.

A simple zener diode would be a good choice without going through the calculation. Besides the simplifying the calculation, zener diode doesn't consumes power at heavy load condition, which helps to improve the converter heavy-load efficiency.

A simple resistor can also be used to limit the output voltage at no load condition. However, this resistor connects to the output all the time and it reduces the full-load efficiency. The pre-load resistor can be calculated based on below equation or based on experiments. In this equation, the V_{MAX} is allowed maximum output voltage, and V_{REG} is the regulated output voltage.

$$R_L = \frac{4 \times V_{MAX}{}^2 \times (V_{MAX} - V_{REG})}{V_{MAX} + V_{REG}} \times \frac{C_{FB} \times (R_{FB1} + R_{FB2})}{L_1 \times I_{LIMIT}{}^2}$$

(7)

9.2.1.2.6 Inductor (L1)

Initial calculations:

Half of the peak-to-peak ripple current at full load:

$$\Delta I_L = 2 \times (I_{LIMIT} - I_{OUT})$$

(8)

When operating in DCM, the peak-to-peak current ripple is the peak current of the device.

Average MOSFET conduction minimum duty cycle at continuous conduction mode is:

$$D_{MIN} = \frac{V_{OUT} + V_d}{V_{IN(max)} - V_d}$$

(9)

If the converter operates in discontinuous conduction mode:

$$D_{MIN} = 2 \times \frac{I_{OUT}}{I_{LIMIT}} \frac{V_{OUT} + V_d}{V_{IN(max)} - V_d}$$

(10)

Maximum allowed switching frequency at $V_{IN(max)}$ and full load:

$$F_{SW\_VIN(max)} = \frac{D_{MIN}}{t_{ON\_TO}}$$

(11)

Switching frequency has a maximum value limit of $f_{SW(max)}$.

The worst case I_{LIMIT} = 315 mA, but assuming ΔI_L = 180 mA.

The converter works in continuous conduction mode ($\Delta I_L < I_{LIMIT}$) so based on V_{OUT} = 13 V, V_d = 0.5 V and $V_{IN(max)}$ = 375 V

$$D_{MIN} = \frac{V_{OUT} + V_d}{V_{IN(max)} - V_d} = 3.61\%$$

(12)

The maximum allowed switching frequency is 62 kHz because the calculated value exceeds it.

$$F_{SW\_VIN(max)} = \frac{D_{MIN}}{t_{ON\_TO}} = 80\,kHz > f_{SW(max)} = 62\,kHz$$

(13)

The duty cycle does not force the MOSFET on time to go below t_{ON_TO}. If $D_{MIN}/T_{ON\_TO} < f_{SW(max)}$, the switching frequency is reduced by current runaway protection and the maximum average switching frequency is lower than $f_{SW(max)}$, the converter can't support full load.

The minimum inductance value satisfies both the following conditions:

$$L > \frac{V_{OUT} + V_d}{\Delta I_L \times F_{SW\_VIN(max)}} = 1\,mH$$

(14)

$$L > \frac{V_{IN(max)}}{I_{LIMIT}} \times t_{ON\_TO} = \frac{375\,V}{315\,mA} \times 450\,ns \cong 536\,\mu H$$

(15)

In the application example, 1 mH is selected as the minimum standard value that satisfy Equation 14 and Equation 15.

9.2.1.2.7 Feedback Path (C$_{FB}$, R$_{FB1}$ and R$_{FB2}$) and Load Resistor (R$_L$)

In low-side buck converter the output voltage is always sensed by the FB pin and UCC28881 internal controller can turn on the MOSFET on VOUT. In high-side buck converter applications the information on the output voltage value is stored on C$_{FB}$ capacitor. This information is not updated in real time. The information on C$_{FB}$ capacitor is updated just after MOSFET turn-off event. When the MOSFET is turned off, the inductor current forces the freewheeling diode (D1 in Figure 16) to turn on and the GND pin of UCC28881 goes negative at -V$_{d1}$ (where V$_{d1}$ is the forward drop voltage of diode D1) with respect to the negative terminal of bulk capacitor (C1 in Figure 16). When D1 is on, through diode D4, the C$_{FB}$ capacitor is charged at V$_{OUT}$ − V$_{d4}$ + V$_{d1}$. Set the output voltage regulation level using Equation 16.

$$\frac{R_{FB1}}{R_{FB2}} = \frac{V_{OUT(T)} - V_{d4} + V_{d1} - V_{FB\_TH}}{V_{FB\_TH}} \cong \frac{V_{OUT(T)} - V_{FB\_TH}}{V_{FB\_TH}}$$

where

- V$_{FB\_TH}$ is the FB pin reference voltage.
- V$_{OUT\_T}$ is the target output voltage.
- R$_{FB1}$, R$_{FB2}$ is the resistance of the resistor divider connected with FB pin (see Figure 16)
- The capacitor C$_{FB}$ after D1 is discharged with a time constant that is τ$_{FB}$ = C$_{FB}$ x (R$_{FB1}$ + R$_{FB2}$).
- Select the time constant τ$_{FB}$, given in Equation 17   (16)

$$\tau_{FB} = C_{FB} \times (R_{FB1} + R_{FB2}) = 0.1 \times C_L \times R_{LOAD}$$

(17)

In this equation, R$_{LOAD}$ is the full load resistor value.

The time constant selection leads to a slight output-voltage increase in no-load or light-load conditions. In order to reduce the output-voltage increase, increase τ$_{FB}$. The drawback of increasing τ$_{FB}$ is t in high-load conditions V$_{OUT}$ could drop.

Because of the nature of sample and hold of output voltage feedback, the feedback loop components need some adjustment after the initial design. The larger time constant of the feedback components leads to lower no-load switching frequency. As the results, the no-load standby power and light-load voltage regulation are improved. Because of larger time constant, at heavier load, the load regulation start to get worse. On the contrast, decreasing the time constant makes the heavy load regulation better but increases the no-load standby power and makes the light-load voltage regulation worse. Some tradeoff is required to make the regulation and standby power. Below table summarizes the relationship between the feedback loop time constant and the load regulation. This can be used for an easy guideline for fine tuning the circuit performance.

Table 3. Feedback Loop Time Constant Adjustment

FEEDBACK LOOP TIME CONSTANT (τ$_{FB}$)	NO-LOAD REGULATION	HEAVY-LOAD OUTPUT VOLTAGE RIPPLE	STANDBY POWER
Increase	Better	Worse	Better
Decrease	Worse	Better	Worse

9.2.1.3 Application Curves

Figure 17 shows the output voltage vs output current. Different curves correspond to different converter AC input voltages. Figure 18 shows efficiency changes vs output power. Different curves correspond to different converter AC input voltages.

Figure 17. Output IV Characteristic

Figure 18. Efficiency vs P$_{OUT}$
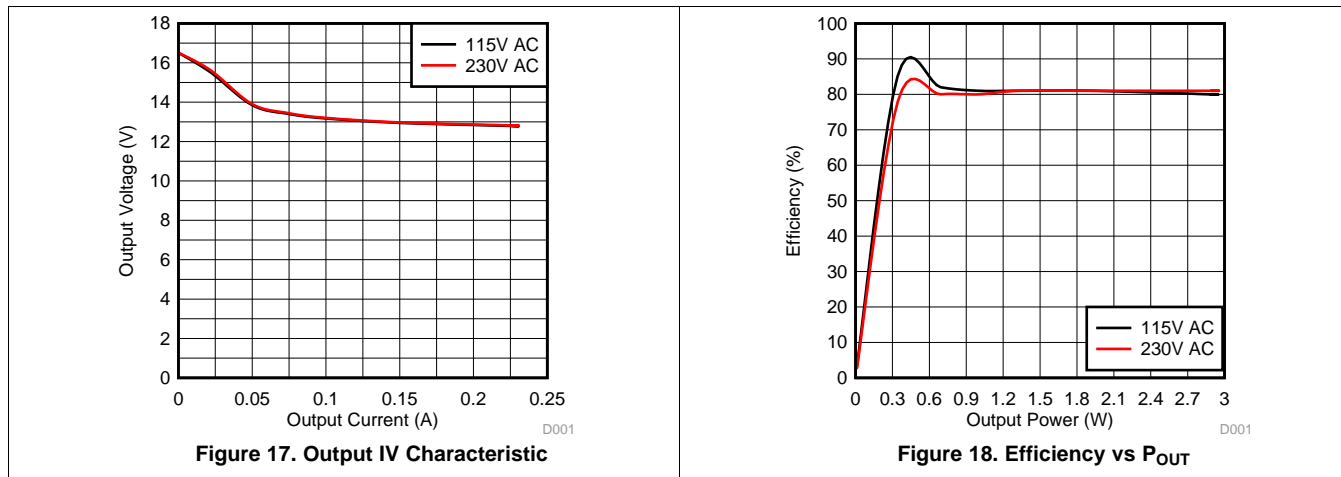
Table 4. Converter Efficiency

V$_{IN\_AC}$ (V$_{RMS}$)	LOAD (mA)	EFFICIENCY (%)	AVERAGE EFFICIENCY (%)
115	50	82	81
	100	81	
	150	81	
	225	80	
230	50	80	80.8
	100	81	
	150	81	
	225	81	

Table 5. Key Component List for 13-V 225-mA High-Side Buck Converter

DES	DESCRIPTION	PART NUMBER	MANUFACTURER[1]
C1, C2	Bulk capacitor, 10 µF, 450 V	EEUED2W100	Panasonic
C$_{FB}$	Feedback capacitor, ceramic, 0.015 µF, 50 V	C0805C153K5RACTU	Kemet
C$_L$	Output capacitor, 330 µF, 35 V	EEU-FM1V331L	Panasonic
D1	Buck freewheeling diode, ultrafast, 600 V, 1 A	STTH1R06A	ST Microelectronics
D2, D3	Rectifier diodes, standard recovery rectifier, 1000 V, 1 A	1N4007	Fairchild semiconductor
D4	Feedback diode, standard recovery rectifier, 600 V, 1 A	1N4006-T	Diodes Inc.
L1	Buck inductor, 1 mH, 0.4 A,	7447471102	Wurth Elektronik
L2	Filter inductor, 1 mH, 0.2 A	5800-102-RC	Bourns
R$_{FB1}$	Upper feedback resistor 121 kΩ, 1%	ERJ-6ENF1213V	Panasonic
R$_{FB2}$	Lower feedback resistor, 10.0 kΩ, 1%	ERJ-6ENF1002V	Panasonic

(1) See *Third-Party Products Discalimer*

9.2.2 Additional UCC28881 Application Topologies

9.2.2.1 Low-Side Buck and LED Driver – Direct Feedback (Level Shifted)

Features include:

- Output Referenced to Input
- Negative Output (V_{OUT}) with Respect to VIN+
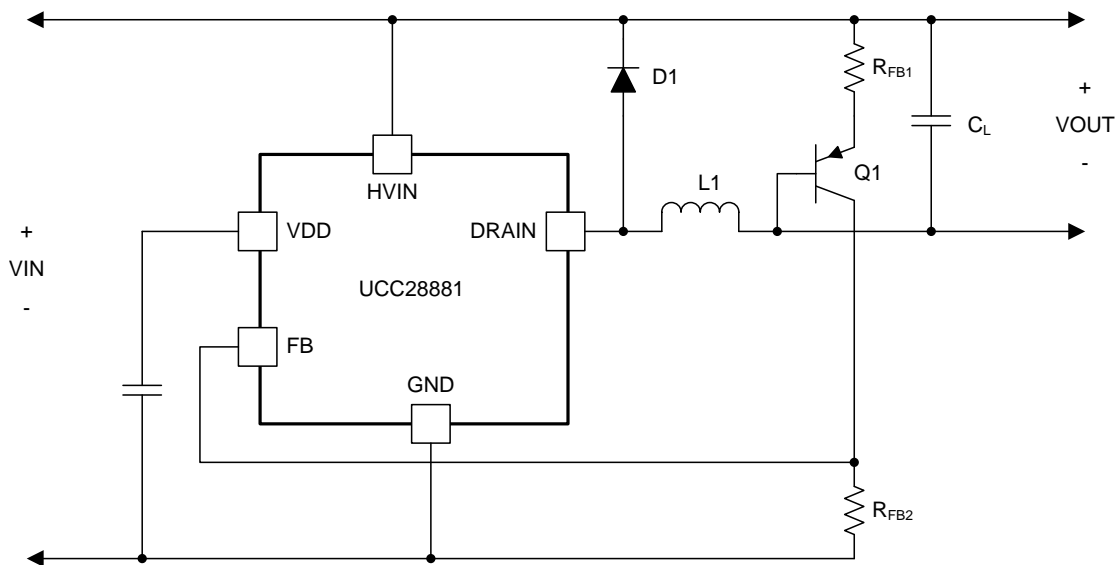- Step Down: $V_{OUT} < V_{IN}$
- Direct Level-Shifted Feedback

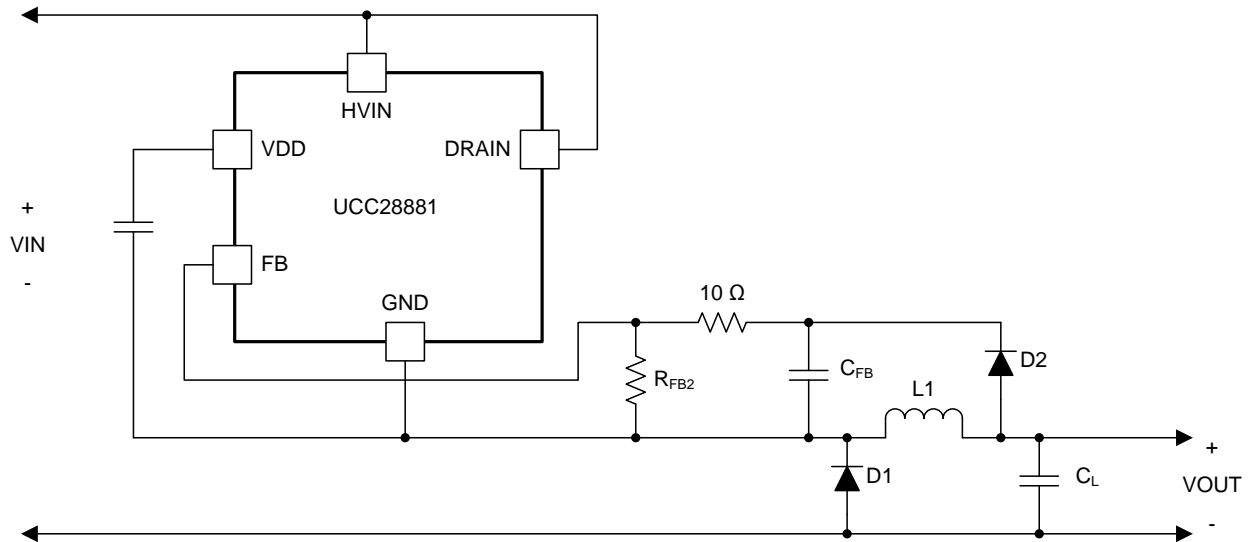**Figure 19. Low-Side Buck, Direct Feedback (Level Shifted)**
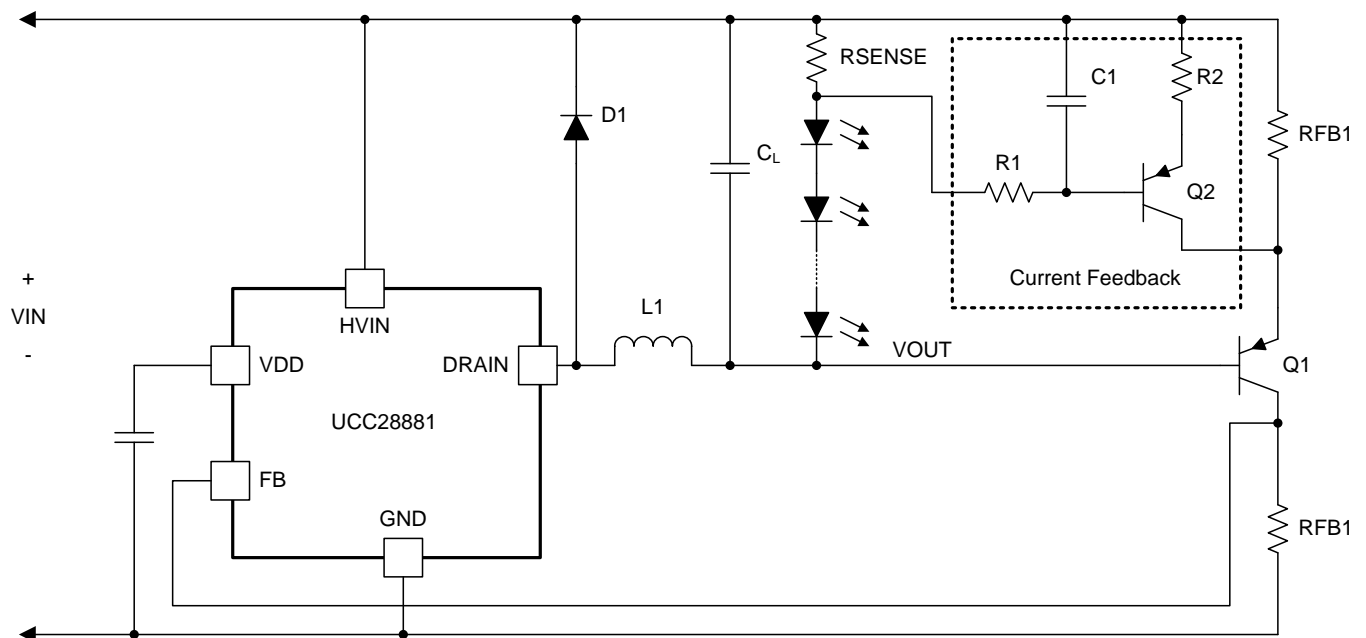
Figure 20. Low-Side Buck LED Driver, Direct Feedback (Level Shifted)

9.2.2.2 High-Side Buck Converter

Features include:

- Output Referenced to Input
- Positive Output (V_{OUT}) with Respect to VIN–
- Step Down ($V_{OUT} < V_{IN}$)

Figure 21. High-Side Buck Converter Schematic

9.2.2.3 Non-Isolated, Low-Side Buck-Boost Converter

Features Include:

- Output Referenced to Input
- Positive Output (V_{OUT}) with Respect to VIN+
- Step Up, Step Down: $V_{OUT} > V_{IN}$ or $V_{OUT} < V_{IN}$
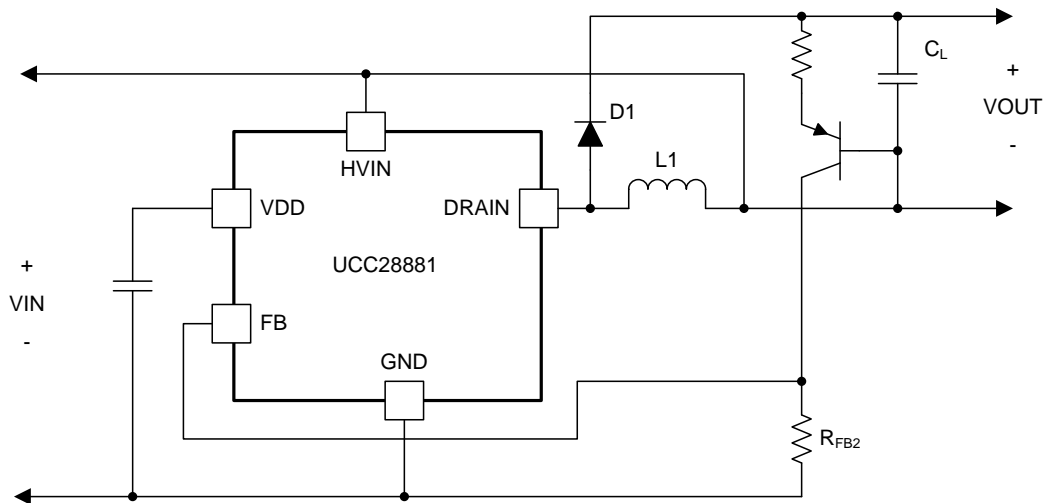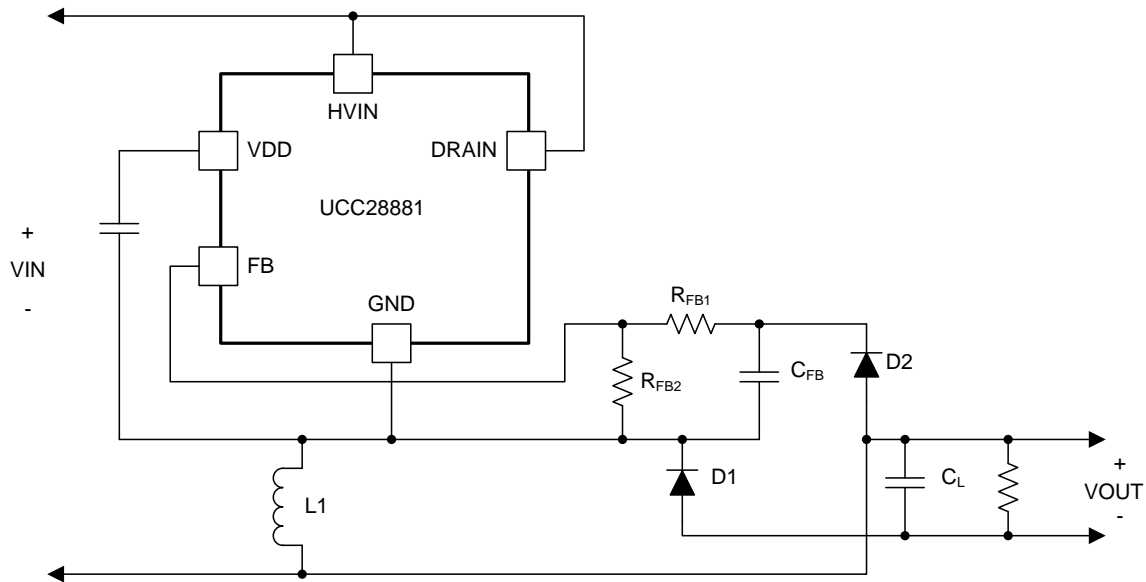- Direct Level-Shifted Feedback

Figure 22. Low-Side Buck-Boost Converter

9.2.2.4 *Non-Isolated, High-Side Buck-Boost Converter*

Features include:

- Output Referenced to Input
- Positive Output (V_{OUT}) with Respect to VIN–
- Step Up, Step Down: $V_{OUT} > V_{IN}$ or $V_{OUT} < V_{IN}$

Figure 23. High-Side Buck-Boost Converter

9.2.2.5 *Non-Isolated Flyback Converter*

Features include:

- Output Referenced to Input
- Positive Output (V_{OUT}) with Respect VIN–
- Direct Feedback
- Higher Output Current Capability, 4.5 W for 85 V_{AC} ~ 265 V_{AC} Input and 6 W for 176 V_{AC} ~ 265 V_{AC} Input
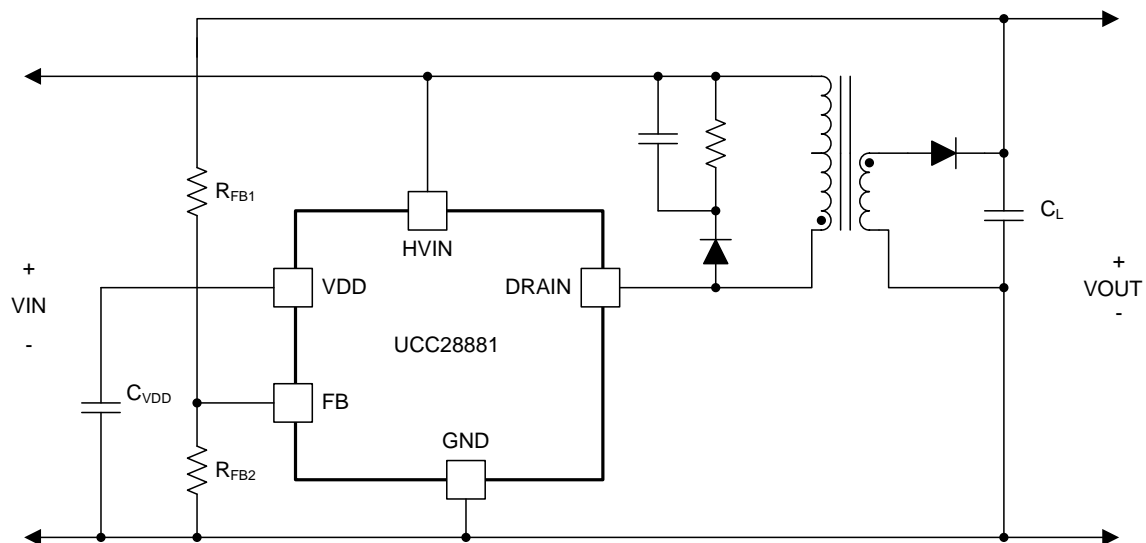

Figure 24. Non-Isolated Flyback Configuration

9.2.2.6 Isolated Flyback Converter

Features include:

*   Output Isolated from Input
*   Direct Feedback
*   Higher Output Current Capability, 4.5 W for 85 V_{AC} ~ 265 V_{AC} Input and 6 W for 176 V_{AC} ~ 265V_{AC} Input
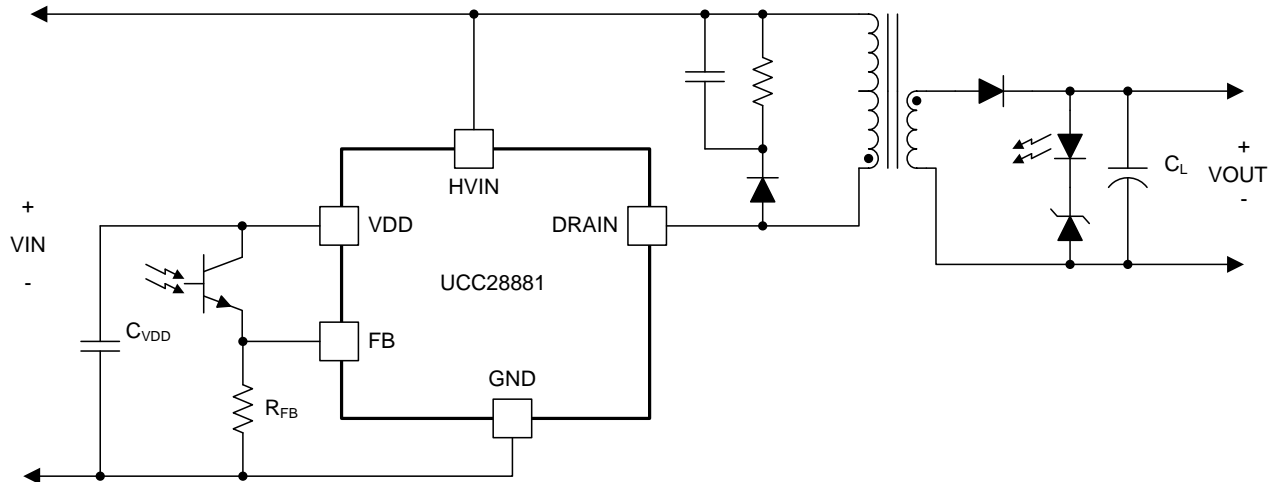

Figure 25. Isolated Flyback Converter

10 Power Supply Recommendations

The VDD capacitor recommended value is 100 nF to ensure high-phase margin of the internal 5-V regulator and it should be placed close to VDD pin and GND pins to minimize the series resistance and inductance.

The VDD pin provides a regulated 5-V output but it is not intended as a supply for external load. Do not supply VDD pin with external voltage source (for example the auxiliary winding of flyback converter).

Always keep GND pin 1 and GND pin 2 connected together with the shortest possible connection.

11 Layout

11.1 Layout Guidelines

- In both buck and buck-boost low-side configurations, the copper area of the switching node DRAIN should be minimized to reduce EMI.
- Similarly, the copper area of the FB pin should be minimized to reduce coupling to feedback path. Loop C_L, Q1, R_{FB1} should be minimized to reduce coupling to feedback path.
- In high-side buck and buck boost the GND, VDD and FB pins are all part of the switching node so the copper area connected with these pins should be optimized. Large copper area allows better thermal management, but it causes more common mode EMI noise. Use the minimum copper area that is required to handle the thermal dissipation.
- Minimum distance between 700-V coated traces is 1.41 mm (60 mils).

11.2 Layout Example

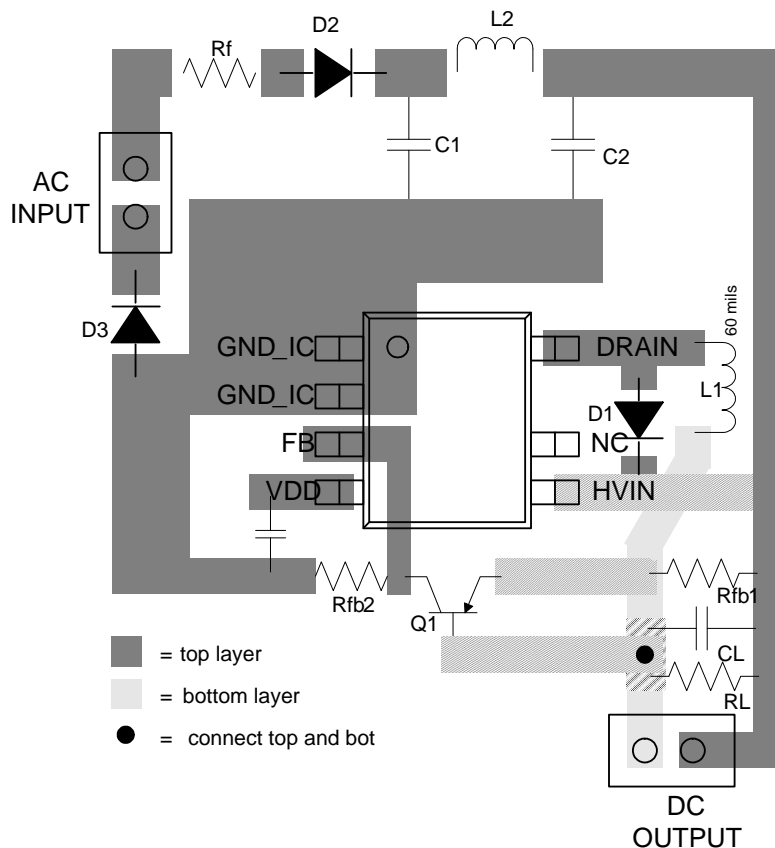Figure 26 shows and example PCB layout for UCC28881 in low-side buck configuration.

Figure 26. UCC28881 Layout Example

12 器件和文档支持

12.1 器件支持

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12.5 Glossary

SLYZ022 — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 机械、封装和可订购信息

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![Texas Instruments logo]

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
UCC28881D	ACTIVE	SOIC	D	7	75	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	U28881	Samples
UCC28881DR	ACTIVE	SOIC	D	7	2500	RoHS & Green	NIPDAU	Level-2-260C-1 YEAR	-40 to 125	U28881	Samples

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
OBSOLETE: TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".
RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.
Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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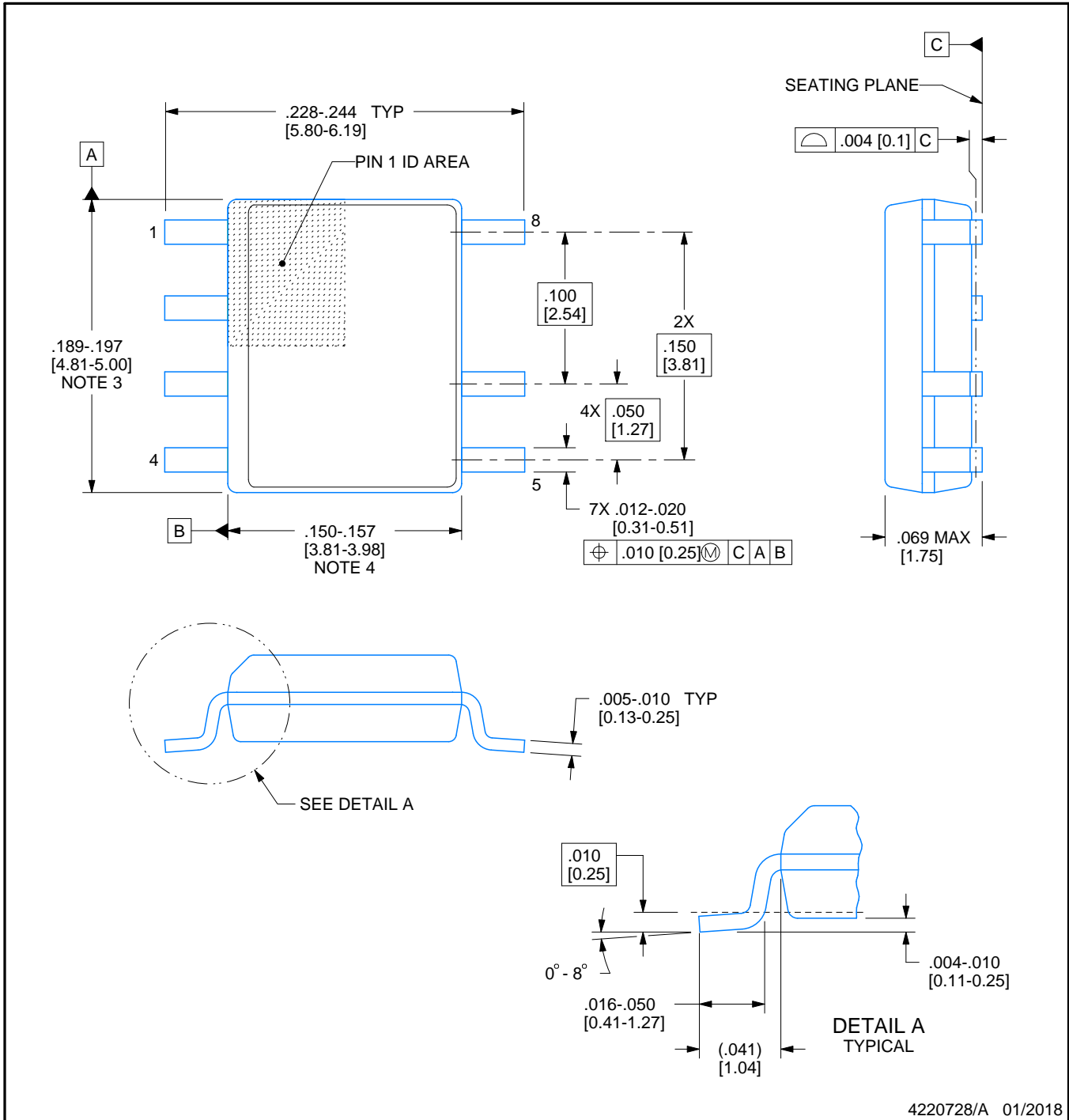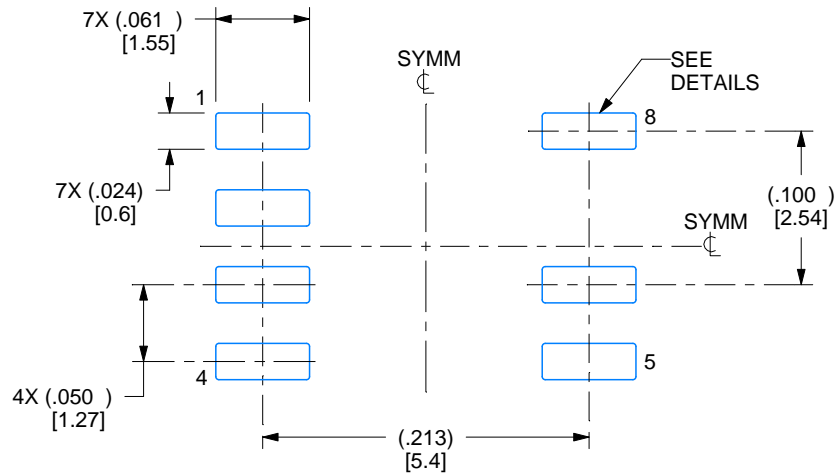
4220728/A   01/2018

NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

7X (.061)
[1.55]

SYMM
₵

SEE
DETAILS

1

8

7X (.024)
[0.6]

SYMM
₵

(.100)
[2.54]

4X (.050)
[1.27]

4

5

(.213)
[5.4]

LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:8X

METAL

SOLDER MASK
OPENING

SOLDER MASK
OPENING

METAL UNDER
SOLDER MASK

EXPOSED
METAL

EXPOSED
METAL

.0028 MAX
[0.07]
ALL AROUND

.0028 MIN
[0.07]
ALL AROUND

NON SOLDER MASK
DEFINED

SOLDER MASK
DEFINED
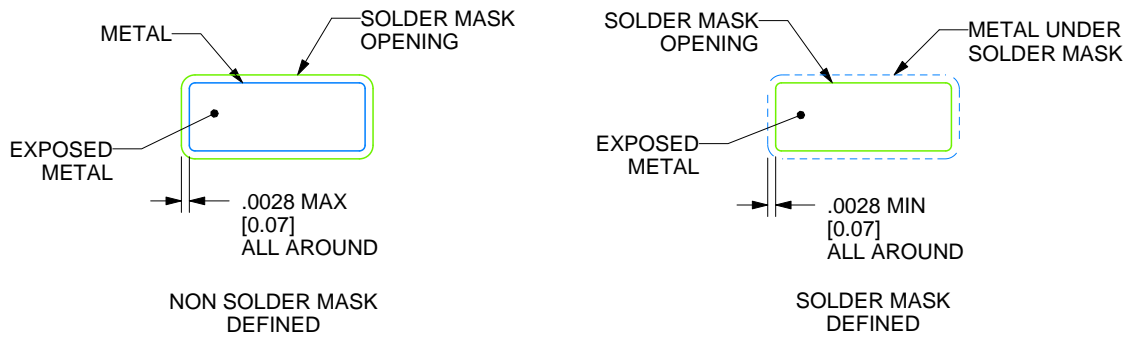
SOLDER MASK DETAILS

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NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

7X (.061)
[1.55]

SYMM

1

7X (.024)
[0.6]

SYMM

(.100)
[2.54]

8

5

4

4X (.050)
[1.27]

(.213)
[5.4]
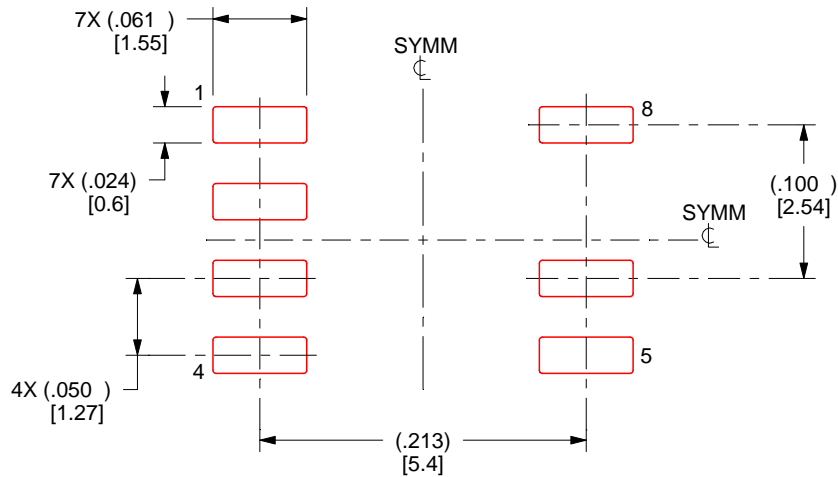
SOLDER PASTE EXAMPLE
BASED ON .005 INCH [0.125 MM] THICK STENCIL
SCALE:8X

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NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate
   design recommendations.
9. Board assembly site may have different recommendations for stencil design.

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