

SLLS842A - JUNE 2009 - REVISED JUNE 2010

Gigabit 8 x 8 CROSSPOINT SWITCH

Check for Samples: SN65LVCP408

FEATURES

- Up to 4.25 Gbps Operation
- Non-Blocking Architecture Allows Each Output to be Connected to Any Input
- 30 ps of Deterministic Jitter
- Selectable Transmit Pre-Emphasis Per Lane
- Selectable Receive Equalization
- Available Packaging 64 Pin QFP
- Propagation Delay Times: 500 ps Typical
- Inputs Electrically Compatible With CML Signal Levels
- Operates From a Single 3.3-V Supply
- Ability to 3-STATE Outputs
- Integrated Termination Resistors
- I²C[™] Control Interface

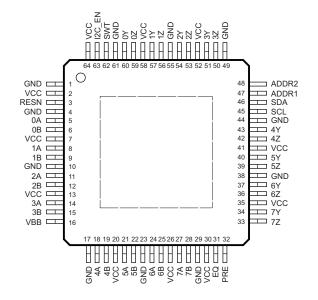
APPLICATIONS

- Clock Buffering/Clock MUXing
- Wireless Base Stations
- High-Speed Network Routing
- Telecom/Datacom
- XAUI 802.3ae Protocol Backplane Redundancy

DESCRIPTION

The SN65LVCP408 is a 8 \times 8 non-blocking crosspoint switch in a flow-through pin-out allowing for ease in PCB layout. VML signaling is used to achieve a high-speed data throughput while using low power. Each of the output drivers includes a 8:1 multiplexer to allow any input to be routed to any output. Internal signal paths are fully differential to achieve the high signaling speeds while maintaining low signal skews. The SN65LVCP408 incorporates 100- Ω termination resistors for those applications where board space is a premium. Built-in transmit pre-emphasis and receive equalization for superior signal integrity performance.

The SN65LVCP408 is characterized for operation from -40° C to 85° C. (See operating free air condition requirements)



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet. PowerPAD is a trademark of Texas Instruments.

 I^2C is a trademark of Philips Electronics.

SN65LVCP408



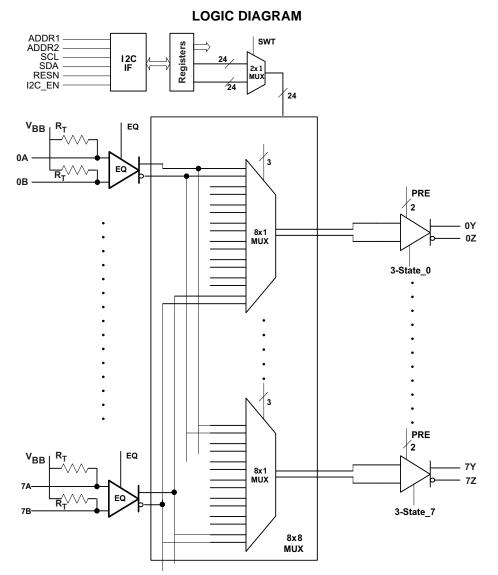
SLLS842A – JUNE 2009 – REVISED JUNE 2010

www.ti.com



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.



A. V_{BB}: Receiver input internal biasing voltage (allows ac coupling)

B. R_T : Internal 50- Ω receiver termination (100- Ω differential)



SN65LVCP408

SLLS842A - JUNE 2009-REVISED JUNE 2010

	PIN FUNCTIONS							
	Pin	TYPE	DECODIDITION					
NAME	NO.	TYPE	DESCRIPTION					
High Speed I/	0							
xA	5, 8, 11, 14, 18, 21, 24 ,27	Differential Inputs (with						
хB	6, 9, 12, 15, 19, 22, 25, 28	50-Ω termination to Vbb) xA=P; xB=N	Line Side Differential Inputs CML compatible					
xY	34, 37, 40 43, 51, 54, 57, 60	Differential Output xY=P;	Switch Side Differential Outputs. VML					
хZ	33, 36, 39, 42, 50, 53, 56, 59	xZ=N						
Control Signa	ls							
SCL	45							
SDA	46	- Inputs	I ² C Control Interface (SCL: Clock, SDA: Data, ADDR:					
ADDR1	47	Inputs	Address)					
ADDR2	48							
EQ	31	Input	Equalization setting when I^2C is not enabled. EQ=0 for 13dB and setting EQ=1 for 9dB.					
PRE	32	Input	Pre-Emphasis setting when I ² C is not enabled. PRE=0 for 0 dB and PRE=1 for 6 dB					
I2C_EN	63	Input	Enables I ² C control interface I ² C_EN=1 for enable; When EN=0 then the PRE and EQ pins are used to set the Pre-Emphasis and Equalization settings rather than the I2C register map. When EN=0 the I ² C register map is still open for read and write operations.					
SWT	62	Input	Enable switch event when toggled					
RESN	3	Input (Active Low)	Configuration Reset. Resets I ² C register space (Active Low). Note upon device startup the RESN pin must be driven low to reset the device registers.					
Power Supply	,		·					
VCC	2, 7, 13, 20, 26, 30, 35, 41, 52, 58, 64	Power	Power Supply 3.3v±5%					
GND	1,4, 10, 17, 23, 29 , 38, 44, 49, 55, 61	Ground						
V _{BB}	16	Input	Receiver input biasing voltage					
PowerPAD™		Ground	The ground center pad of the package must be connected to GND plane.					

TEXAS INSTRUMENTS

SLLS842A - JUNE 2009-REVISED JUNE 2010

EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS

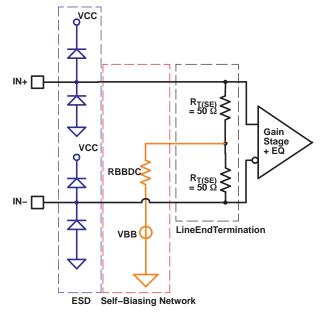


Figure 1. Equivalent Input Circuit Design

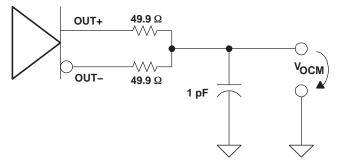


Figure 2. Common-Mode Output Voltage Test Circuit

AVAILABLE OPTIONS⁽¹⁾

.	DESCRIPTION	PACKAGED DEVICE ⁽²⁾
I A	DESCRIPTION	PAP (64 pin)
-40°C to 85°C	Serial multiplexer	SN65LVCP408

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

(2) The package is available taped and reeled. Add an R suffix to device types (e.g., SN65LVCP408PAP). Temperature range assumes 1 m/s airflow.

PACKAGE THERMAL CHARACTERISTICS

PACKAGE THERMAL CHARACTER	NOM	UNIT	
θ_{JA} (junction-to-ambient)	100LFM airflow is required otherwise a 4x4 thermal via array must be implemented with 6 layer or greater PCB.	21.2	°C/W

(1) See application note SPRA953 for a detailed explanation of thermal parameters (http://www-s.ti.com/sc/psheets/spra953/spra953.pdf).



SLLS842A - JUNE 2009-REVISED JUNE 2010

www.ti.com

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range (unless otherwise noted)⁽¹⁾

			UNIT
V _{CC}	Supply voltage range ⁽²⁾		–0.5 V to 6 V
	Voltogo rongo	Control inputs, all outputs	-0.5 V to (V _{CC} + 0.5 V)
	Voltage range	Receiver inputs	–0.5 V to 4 V
	Human Body Model ⁽³⁾	All pins	6 kV
ESD	Charged-Device Model ⁽⁴⁾	All pins	500 V
TJ	Maximum junction temperature		See Package Thermal Characteristics Table
	Moisture sensitivity level		2
	Reflow temperature package soldering, 4 seconds		260°C

(1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.

(3) Tested in accordance with JEDEC Standard 22, Test Method A114-A.

(4) Tested in accordance with JEDEC Standard 22, Test Method C101.

RECOMMENDED OPERATING CONDITIONS

			MIN	NOM	MAX	UNIT
dR	Operating data rate				4.25	Gbps
V _{CC}	Supply voltage		3.135	3.3	3.465	V
V _{CC(N)}	Supply voltage noise amplitude	10 Hz to 2.125 GHz			20	mV
TJ	Junction temperature				125	°C
T _A	Operating free-air temperature ⁽¹⁾	Assumes 4x4 thermal via array is implemented with 6 layer or greater PCB otherwise 100LFM airflow is required.	-40		85	°C
DIFFERE	ENTIAL INPUTS					
		dR _(in) ≤ 4.25 Gbps	100		1750	mV_{PP}
V _{ID}	Receiver peak-to-peak differential input voltage ⁽²⁾	1.25 Gbps < dR _(in) ≤ 4.25 Gbps	100		1560	mV_{PP}
	voltage	dR _(in) > 4.25 Gbps	100	100 1560	mV_{PP}	
V _{ICM}	Receiver common-mode input voltage	Note: for best jitter performance ac coupling is recommended.	1.5	1.6 \	$V_{\rm CC} - \frac{ V_{\rm ID} }{2}$	V
CONTRO	DL INPUTS					
V _{IH}	High-level input voltage		2		V _{CC} + 0.3	V
V _{IL}	Low-level input voltage		-0.3		0.8	V
DIFFERE	ENTIAL OUTPUTS					
R _L	Differential load resistance		80	100	120	Ω

(1) Maximum free-air temperature operation is allowed as long as the device maximum junction temperature is not exceeded.

(2) Differential input voltage V_{ID} is defined as | IN+ - IN- |.

TEXAS INSTRUMENTS

www.ti.com

ELECTRICAL CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIO	NS	MIN	TYP ⁽¹⁾	MAX	UNIT	
DIFFEREN	ITIAL INPUTS							
V _{IT+}	Positive going differential input high threshold					50	mV	
V _{IT-}	Negative going differential input low threshold			-50			mV	
A _(EQ)	Equalizer gain	at 1.875 GHz (EQ=1)			9		dB	
R _{T(D)}	Termination resistance, differential			80	100	120	Ω	
V _{BB}	Open-circuit Input voltage (input self-bias voltage)	AC-coupled inputs			1.6		V	
R _(BBDC)	Biasing network dc impedance				30		kΩ	
D	Biasing network ac	375 MHz			42		Ω	
R _(BBAC)	impedance	2.125 GHz		8.4			Ω	
DIFFEREN	ITIAL OUTPUTS							
V _{ODH}	High-level output voltage				650		mV _{PP}	
V _{ODL}	Low-level output voltage	 R _L = 100 Ω ±1%, Pre-Emph=0 dB	4		-650		mV _{PP}	
V _{ODB}	Output differential voltage without preemphasis ⁽²⁾		1000	1300	1500	mV _{PP}		
V _{OCM}	Output common mode voltage				1.8		V	
$\Delta V_{OC(SS)}$	Change in steady-state common-mode output voltage between logic states	See Figure 2		1		mV		
	Output preemphasis voltage ratio,				0			
V _(PE)	V _{ODB(PP)}	$R_L = 100 \Omega \pm 1\%$; x = L or S; See Figure 3		6			dB	
	$\overline{V_{ODPE(PP)}}$				10			
t _(PRE)	Preemphasis duration measurement	Output preemphasis is set to 10 d Measured with a 100-MHz clock s $R_L = 100 \Omega \pm 1\%$, See Figure 4			175		ps	
r _o	Output resistance	Differential on-chip termination be OUT-	tween OUT+ and		100		Ω	
CONTROL	. INPUTS	1						
I _{IH}	High-level Input current	VIN = VCC				5	μA	
IIL	Low-level Input current	VIN = GND		-125	-90		μA	
R _(PU)	Pullup resistance				35		kΩ	
POWER C	ONSUMPTION							
P _D	Device power dissipation	All outputs terminated 100 $\boldsymbol{\Omega}$				1.52	W	
Pz	Device power dissipation in 3-State	All outputs in 3-state	PRBS 2 ⁷⁻¹ pattern at 4.25			864	mW	
I _{CC}	Device current consumption	All outputs terminated 100 Ω	Gbps			440	mA	

(1) All typical values are at T_A = 25°C and V_{CC} = 3.3 V supply unless otherwise noted. They are for reference purposes and are not production tested.
 (2) Differential extension of the free days of the set of the

(2) Differential output voltage $V_{(ODB)}$ is defined as | OUT+ – OUT– |.



SLLS842A -JUNE 2009-REVISED JUNE 2010

www.ti.com

SWITCHING CHARACTERISTICS

over operating free-air temperature range (unless otherwise noted)

	PARAMETER	RAMETER TEST CONDITIONS			MIN	TYP ⁽¹⁾	MAX	UNIT
MULTI	PLEXER							
t _(SM)	Multiplexer switch time	Multiplexer to valid output					15	ns
DIFFE	RENTIAL OUTPUTS	L						
t _{PLH}	Low-to-high propagation delay		Descention delay insult to autout Oce Figure C			0.5	0.7	ns
t _{PHL}	High-to-low propagation delay	Propagation delay input to output, See Figure 6				0.5	0.7	ns
t _r	Rise time	20% to 80% of V _{O(DB)} ; Test	Pattern: 100-MH	z clock signal;		90		ps
t _f	Fall time	See Figure 5 and Figure 8	See Figure 5 and Figure 8			90		ps
t _{sk(p)}	Pulse skew, t _{PHL} – t _{PLH} ⁽²⁾						20	ps
t _{sk(o)}	Output skew ⁽³⁾	All outputs terminated with 1	All outputs terminated with 100 Ω			25	75	ps
t _{sk(pp)}	Part-to-part skew ⁽⁴⁾						150	ps
t _{zd}	3-State switch time to Disable	Assumes 50 Ω to Vcm and 2 Tested using I2C	Assumes 50 Ω to Vcm and 150 pF load on each output; Tested using I2C				30	ns
t _{ze}	3-State switch time to Enable	Assumes 50 Ω to Vcm and 150 pF load on each output; Tested using I2C					20	ns
RJ	Device random jitter, rms	See Figure 8 for test circuit. Alternating 10-pattern.	BERT setting 10	-15		0.8	2	ps-rms
	Intrinsic deterministic device jitter ⁽⁵⁾ , peak-to-peak	0 dB preemphasis See Figure 8 for the test circuit.	PRBS 2 ⁷⁻¹ pattern	4.25 Gbps			30	ps
DJ		0 dB preemphasis	DDD0 0 ⁷⁻¹	1.25Gbps; EQ=13dB Over 25-inch FR4 trace		15		
	Absolute deterministic output jitter ⁽⁶⁾ , peak-to-peak	See Figure 8 for the test circuit.	PRBS 2 ⁷⁻¹ pattern	4.25 Gbps; EQ=13dB Over FR4 trace 2-inch to 43 inches long		40		ps

(1) All typical values are at 25°C and with 3.3 V supply unless otherwise noted.

(2) t_{sk(p)} is the magnitude of the time difference between the t_{PLH} and t_{PHL} of any output of a single device.

(3) $t_{sk(o)}$ is the magnitude of the time difference between the t_{PLH} and t_{PHL} of any two outputs of a single device.

(4) t_{sk(pp)} is the magnitude of the difference in propagation delay times between any specified terminals of two devices when both devices operate with the same supply voltages, at the same temperature, and have identical packages and test circuits.

(5) The SN65LVCP408 built-in passive input equalizer compensates for ISI. For a 25-inch FR4 transmission line with 8-mil trace width, the LVCP408 typically reduces jitter by 29 ps from the device input to the device output.

(6) Absolute deterministic output jitter reflects the deterministic jitter measured at the SN65LVCP408 output. The value is a real measured value with a Bit error tester as described in Figure 8. The absolute DJ reflects the sum of all deterministic jitter components accumulated over the link: DJ_(absolute) = DJ_(Signal generator) + DJ_(transmission line) + DJ_{(intrinsic(LVCP408))}.

SLLS842A – JUNE 2009 – REVISED JUNE 2010

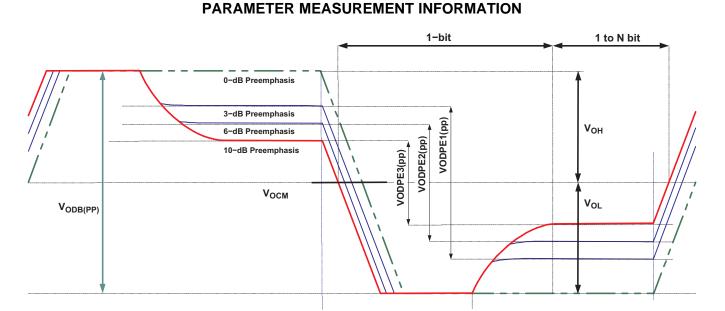


Figure 3. Preemphasis and Output Voltage Waveforms and Definitions

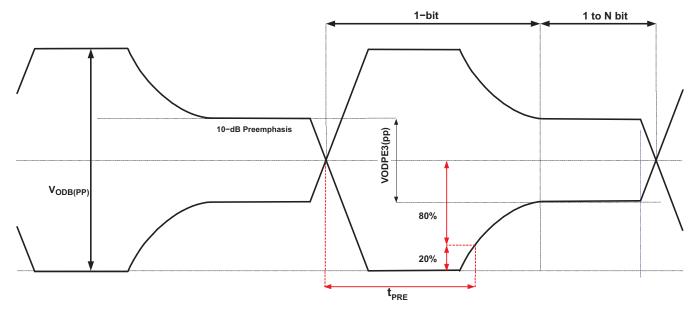


Figure 4. t_{(PRE}) Preemphasis Duration Measurement

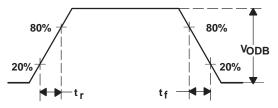


Figure 5. Driver Output Transition Time



SN65LVCP408

www.ti.com

SLLS842A - JUNE 2009 - REVISED JUNE 2010

PARAMETER MEASUREMENT INFORMATION (continued)

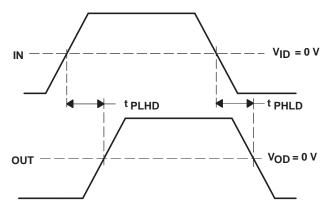
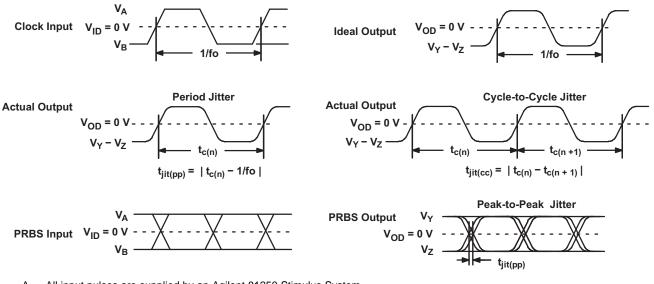


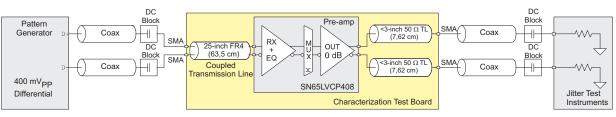
Figure 6. Propagation Delay Input to Output



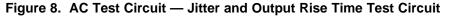
A. All input pulses are supplied by an Agilent 81250 Stimulus System.

B. The measurement is made with the AgilentParBert measurement software.

Figure 7. Driver Jitter Measurement Waveforms



For the rise/fall time measurements, the 25-inch FR4 transmission line is removed.



The SN65LVCP408 input equalizer provides frequency gain to compensate for frequency loss of a shorter backplane transmission line. For characterization purposes, a 25-inch (63,5 cm) FR-4 coupled transmission line is used in place of the backplane trace. The 25-inch trace provides roughly 5 dB of attenuation between 375 MHz and 2.125 GHz, representing closely the characteristics of a short backplane trace. The loss tangent of the FR4 in the test board is 0.018 with an effective $\varepsilon(r)$ of 4.1.

Copyright © 2009–2010, Texas Instruments Incorporated



TYPICAL DEVICE BEHAVIOR

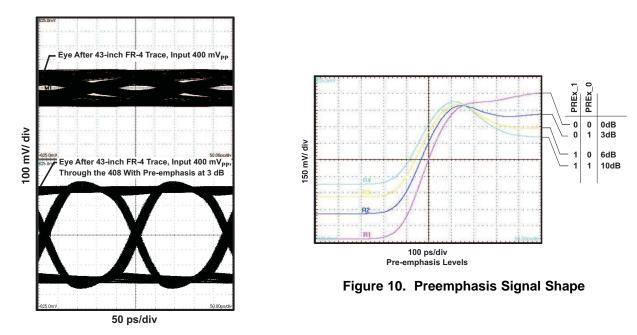


Figure 9. Data Input and Output Pattern

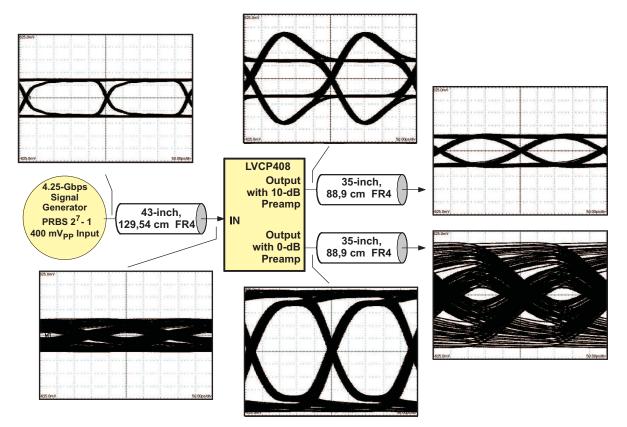


Figure 11. Data Output Pattern

SN65LVCP408



www.ti.com

SLLS842A - JUNE 2009-REVISED JUNE 2010

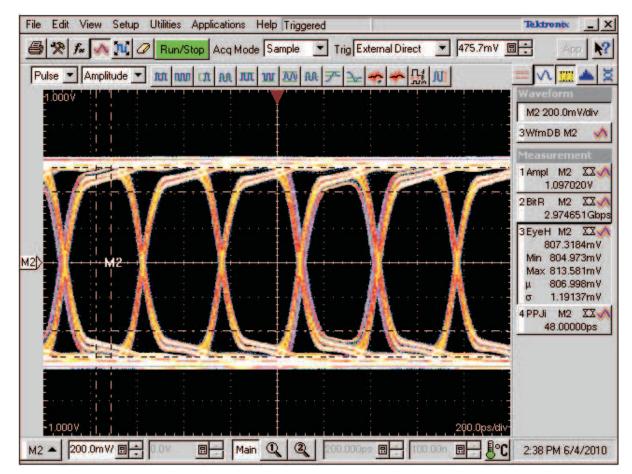


Figure 12. SN65LVCP408 Passing 3G (2.97Gbps) SDI Pathological Data Pattern DC Coupled Environment

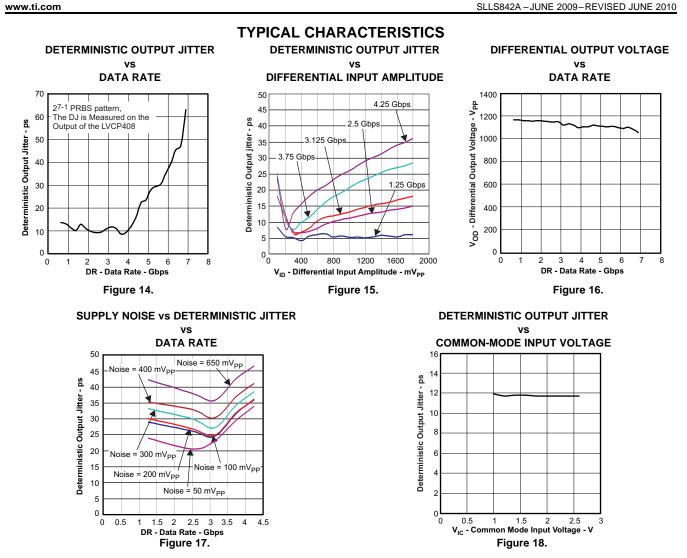
Copyright © 2009–2010, Texas Instruments Incorporated

SLLS842A – JUNE 2009 – REVISED JUNE 2010

File Edit View Setup	Utilities Applications	Help Triggered			Tektronix _ X
🗃 🛠 f* 🚺 🖉	Run/Stop Acq Mode	e Sample 💌 Trig	External Direct	475.7mV 🖪	E App 💦
Pulse 💌 Amplitude 💌	AT AN CA AA AA	W W # 7	<u>}</u>	0	= 🔨 🧰 🔺 🕱
1.000 / / / / / / / /		Y			Waveform M2 200.0m V/div
					3WfmDB M2 🚮
TAT	es e	16			1 Ampl M2 XX
					2 Bit R M2 XX 3.015386 Gbps
12)					3EyeH M2 ΣΣ 774.7238mV Min 769.171mV Max 774.872mV μ 774.368mV σ 647.058μV
					4 PPJi M2 XX 44.00000ps
1,000V				200.0ps/div	
M2 A 200.0mV/ .	0.0V 🖳 Main	Q Q 200.0	100ps	8°℃	3:16 PM 6/4/2010

Figure 13. SN65LVCP408 Passing 3G (2.97Gbps) SDI Pathological Data Pattern AC Coupled Environment

SLLS842A -JUNE 2009-REVISED JUNE 2010



SLLS842A - JUNE 2009-REVISED JUNE 2010



www.ti.com

I²C CONTROL INTERFACE

I²C Interface Notes

The I²C interface is used to access the internal registers of the SN65LVCP408. I²C is a two-wire serial interface developed by Philips Semiconductor (see I²C-Bus Specification, Version 2.1, January 2000). The bus consists of a data line (SDA) and a clock line (SCL) with pull-up structures. When the bus is idle, both SDA and SCL lines are pulled high. All the I²C compatible devices connect to the I²C bus through open drain I/O pins, SDA and SCL. A master device, usually a microcontroller or a digital signal processor, controls the bus. The master is responsible for generating the SCL signal and device addresses. The master also generates specific conditions that indicate the START and STOP of data transfer. A slave device receives and/or transmits data on the bus under control of the master device. The SN65LVCP408 works as a slave and supports the standard mode transfer (100 kbps).

The basic I²C start and stop access cycles are shown in Figure 19. The basic access cycle consists of the following:

- A start condition
- A slave address cycle
- Any number of data cycles
- A stop condition

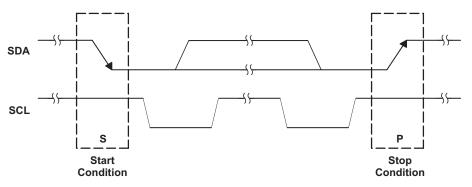


Figure 19. I²C Start and Stop Conditions

General I²C Protocol

- The master initiates data transfer by generating a start condition. The start condition is when a high-to-low transition occurs on the SDA line while SCL is high, as shown in Figure 19. All I²C-compatible devices should recognize a start condition.
- The master then generates the SCL pulses and transmits the 7-bit address and the read/write direction bit R/W on the SDA line. During all transmissions, the master ensures that data is valid. A valid data condition requires the SDA line to be stable during the entire high period of the clock pulse (see Figure 20). All devices recognize the address sent by the master and compare it to their internal fixed addresses. Only the slave device with a matching address generates an acknowledge (see Figure 21) by pulling the SDA line low during the entire high period of the ninth SCL cycle. On detecting this acknowledge, the master knows that a communication link with a slave has been established.
- The master generates further SCL cycles to either transmit data to the slave (R/W bit 0) or receive data from the slave (R/W bit 1). In either case, the receiver needs to acknowledge the data sent by the transmitter. So an acknowledge signal can either be generated by the master or by the slave, depending on which one is the receiver. The 9-bit valid data sequences consisting of 8-bit data and 1-bit acknowledge can continue as long as necessary (see Figure 22).
- To signal the end of the data transfer, the master generates a stop condition by pulling the SDA line from low
 to high while the SCL line is high (see Figure 19). This releases the bus and stops the communication link
 with the addressed slave. All I²C compatible devices must recognize the stop condition. Upon the receipt of a
 stop condition, all devices know that the bus is released, and they wait for a start condition followed by a
 matching address.
- All bytes are transmitted most significant bit first.



SN65LVCP408

μS

μS

μS

SLLS842A -JUNE 2009-REVISED JUNE 2010

www.ti.com

f_{SCL}

t_{W(L)}

t_{W(H)}

t_{SU1}

t_{h(1)}

t_(buf)

t_{su(2)}

t_{h(2)}

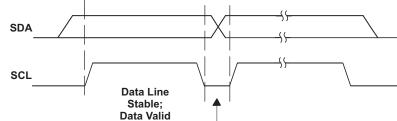
t_{su(3)}

Table 1. I²C Timing **TEST CONDITIONS** PARAMETER MIN TYP MAX UNIT Local I²C SCL clock frequency for internal register 100 kHz Local I²C Clock LOW period for I²C register 4.7 μS Local I²C Clock HIGH period for internal register 4 μS Internal register setup time, SDA to SCL Local I²C 250 μS Local I²C Internal register hold time, SCL to SDA 0 μs Internal register bus free time between STOP Local I²C 4.7 μS and START

Local I²C

Local I²C

Local I²C



— Change of Data Allowed

4.7

4

4



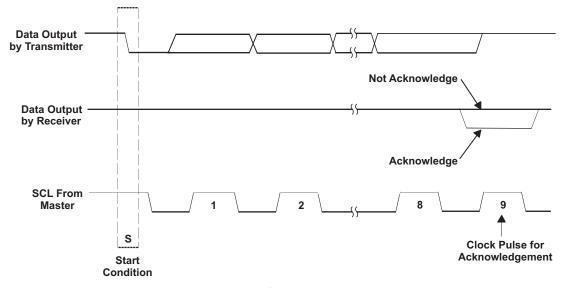


Figure 21. I²C Acknowledge

Note: Following power up, this device must be reset.

Internal register setup time, SCL to START

Internal register hold time, START to SCL

Internal register hold time, SCL to STOP

SLLS842A-JUNE 2009-REVISED JUNE 2010



www.ti.com

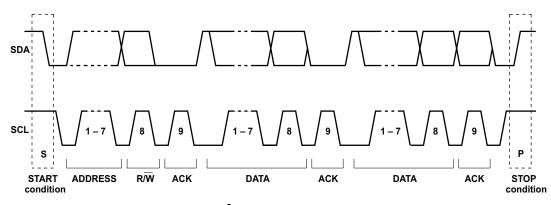
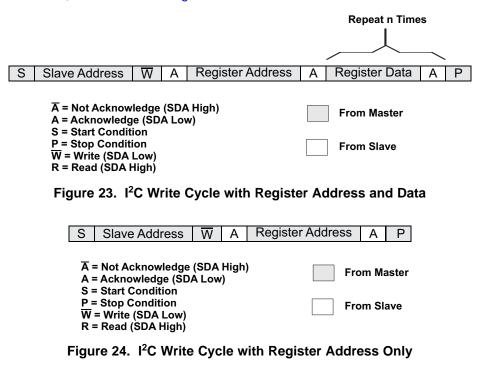


Figure 22. I²C Address and Data Cycles

During a write cycle, the slave sends an acknowledge (A) after every byte that follows the device address. The first byte following the device address is the register address, which maps to the register addresses specific to the device. The second byte following the device address is the data byte to be written at the register address (see Figure 23). If only the register address is to be written for a subsequent read sequence, the data byte is omitted and the sequence ends with a Stop (see Figure 24) or a repeated Start after the register address byte (see Figure 26). If multiple data bytes are to be written at subsequent register addresses, the master may continue to send data bytes after each slave acknowledge, and the slave device automatically increments the register address. Note that the master must not drive the SDA signal line during the slave acknowledge since the slave is in control of the SDA bus and may be holding it low.

During a read cycle, the slave acknowledges the initial address byte if it decodes the device address as its own device address. Following this initial acknowledge by the slave, the master device becomes a receiver and acknowledges data bytes sent by the slave. The first byte received by the master is the data stored at the register address, while subsequent bytes are data stored at incrementing register addresses. When the master has received all of the requested data bytes from the slave, the not acknowledge (Ā) condition is initiated by the master by keeping the SDA signal high just before it asserts the Stop (P) condition. This sequence terminates a read cycle as shown in Figure 25. A combined format is when the read cycle is preceded by a write cycle for setting the register address, and is shown in Figure 26.



Copyright © 2009–2010, Texas Instruments Incorporated



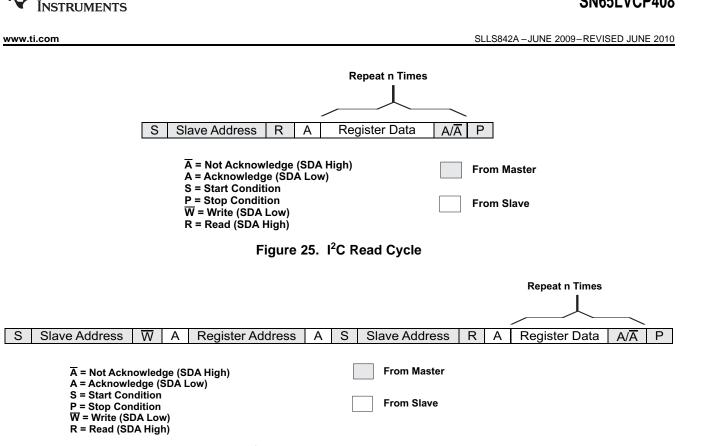


Figure 26. I²C Combined Format Write/Read Cycle

Slave Address

Both SDA and SCL must be connected to a positive supply voltage via a pull-up resistor. These resistors should comply with the I²C specification that ranges from 2 k Ω to 19 k Ω . When the bus is free, both lines are high. The slave address is the first 7 bits received following the START condition from the master device. The first 5 Bits (MSBs) of the address are factory preset to 01011. The next two bits of the SN65LVCP408 address are controlled by the logic levels appearing on the ADDR2 and ADDR1 pins. The ADDR2 and ADDR1 address inputs can be connected to VCC for logic 1, GND for logic 0, or can be actively driven by TTL/CMOS logic levels. The device addresses are set by the state of these pins and are not latched. Thus a dynamic address control system could be utilized to incorporate several devices on the same system. Up to four SN65LVCP408 devices can be connected to the same I²C-Bus without requiring additional glue logic. Table 2 lists the possible addresses for the SN65LVCP408.

		i unit				
			Selectable with	n Address Pins		
Bit 6 (MSB)	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1(addr2)	Bit 0 (addr1)
0	1	0	1	1	0	0
0	1	0	1	1	0	1
0	1	0	1	1	1	0
0	1	0	1	1	1	1

Table 2, Slave Addresses

Note: Following power up, this device must be reset.

SLLS842A – JUNE 2009 – REVISED JUNE 2010

www.ti.com

Table 3. Port Register Addresses

Register Name	Register Address
Output Port 0	0000 0000
Output Port 1	0000 0001
Output Port 2	0000 0010
Output Port 3	0000 0011
Output Port 4	0000 0100
Output Port 5	0000 0101
Output Port 6	0000 0110
Output Port 7	0000 0111
Input Port 0	0000 1000
Input Port 1	0000 1001
Input Port 2	0000 1010
Input Port 3	0000 1011
Input Port 4	0000 1100
Input Port 5	0000 1101
Input Port 6	0000 1110
Input Port 7	0000 1111
Switch Control	0001 0000
Reserved for TI use	0001 0001 to 0001 1010

Table 4. Output Port Control Registers

Bit	Function	Default	Note	Access		
7	0		Selects the desired input port to be used by the output port. Defaults to same			
6	Input Port Select No.1	Input Port Select 0 port number as the ounut port. Valid values are 000 for port 1,001 for port				
5	110.1	0	1etc	R/W		
4			Pre-Emphasis setting. Valid Values are: 00 = 0 dB; 01 = 3 dB; 10 = 6dB, and			
3	Pre-Emphasis	00	11= 10dB; Note When EN=0 then the PRE pin is used to set the Pre-Emphasis setting rather than the I2C register map.			
2	Port 3-State	0	3-State Off = 0; 3-State On=1			
1	RSVD	0	Reserved	Р		
0	RSVD	0	Reserved	R		

Table 5. Input Port Control Registers

Bit	Function	Default	Note	Access
7	Rx Equalization Select	0	Rx Equalization Setting; $0 = 13$ dB; $1 = 9$ dB; Note When EN=0 then the EQ pin is used to set the Equalization setting rather than the I2C register map.	
6	0		Selects the desired input port to be used by the ouput port when the switch even	
5	Input Port Select No.2	0	is triggered. Defaults to same port number as the ouput port. Valid values are :	
4	0		000 for port 0, 001 for port 1etc	
3	RSVD	0	Reserved	
2	RSVD	0	Reserved	Р
1	RSVD	0	Reserved	R
0	RSVD	0	Reserved	

Note: Following power up, this device must be reset.



Bit	Function	Default	Note	Access	
7	Enable Switch Via Pin	0	0= Switch Via I ² C bit is used to enable the switch event; 1 = Switch via SWT pin; When SWT is logic 0, Port Select No. 1 settings will be used. When SWT is logic 1, the Port Select No. 2 settings will be used. The Switch Via i2C setting will be ignored.	R/W	
6	Switch Via I ² C	0	Selects between Port Select No. 1 and No. 2 when enable Switch Via Pin is 0. 0= Port Select No. 1, 1=Port Select No. 2		
5	RSVD	0	Reserved		
4	RSVD	0	Reserved		
3	RSVD	0	Reserved	D	
2	RSVD	0	Reserved	R	
1	RSVD	0	Reserved		
0	RSVD	0	Reserved		

Table 6. Switch Control

Table 7. Reserved for TI Use

Bit	Function	Default	Note	Access
7:0	RSVD	-	Read only value is indeterministic	R

Switching Options

For each output port, users can select two possible input port selection profiles (i.e. sources that indicate which input port to use for the ouput). Input port select No. 1 I^2C^{TM} register bits are used to select the configuration of each output port that is used for default operation. (Note: on power up and after resetting the I2C register space with the RESN pin, each output port is mapped to its matching input port. For example, output port 0 is mapped to input port 0, and output port 1 is mapped to input port 1, etc.). Input Port Select No. 2 registers are used to select the secondary output port configuration that is used when the switch event is triggered.

Triggering Switch Event

Switching between the active output port configuration and the secondary output port configuration (configuration selected with Input Port Select No 2 registers) is accomplished in two ways:

- 1. The switch event can be triggered using the I^2C register bit Switch Via I^2C and setting it to 1 (high).
- 2. If the switch event needs to occur faster than the I²C access allows, then users have the option to use the SWT pin (pin #62) to trigger the switch from port configuration No. 1 to port configuration No. 2. For this option, users should set the Enable Switch Via I²C register bit to 1 upon initial start up. The SWT pin should be logic high state to initiate the switch. Changing the logic states of the SWT pin causes the port configurations to move between the two port configuration options.

APPLICATION INFORMATION

BANDWIDTH REQUIREMENTS

Error free transmission of data over a transmission line has specific bandwidth demands. It is helpful to analyze the frequency spectrum of the transmit data first. For an 8B10B coded data stream at 3.75 Gbps of random data, the highest bit transition density occurs with a 1010 pattern (1.875 GHz). The least transition density in 8B10B allows for five consecutive ones or zeros. Hence, the lowest frequency of interest is 1.875 GHz/5 = 375 MHz. Real data signals consist of higher frequency components than sine waves due to the fast rise time. The faster the rise time, the more bandwidth becomes required. For 80-ps rise time, the highest important frequency component is at least 0.6/(π × 80 ps) = 2.4 GHz. Figure 27 shows the Fourier transformation of the 375-MHz and 1.875-GHz trapezoidal signal.

Copyright © 2009–2010, Texas Instruments Incorporated

SLLS842A - JUNE 2009-REVISED JUNE 2010

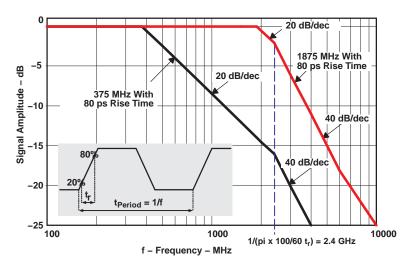


Figure 27. Approximate Frequency Spectrum of the Transmit Output Signal With 80 ps Rise Time

The spectrum analysis of the data signal suggests building a backplane with little frequency attenuation up to 2 GHz. This is achievable only with expensive, specialized PCB material. To support material like FR4, a compensation technique is necessary to compensate for backplane imperfections.

EXPLANATION OF EQUALIZATION

Backplane designs differ widely in size, layer stack-up, and connector placement. In addition, the performance is impacted by trace architecture (trace width, coupling method) and isolation from adjacent signals. Common to most commercial backplanes is the use of FR4 as board material and its related high-frequency signal attenuation. Within a backplane, the shortest to longest trace lengths differ substantially – often ranging from 8 inches up to 40 inches. Increased loss is associated with longer signal traces. In addition, the backplane connector often contributes a good amount of signal attenuation. As a result, the frequency signal attenuation for a 300-MHz signal might range from 1 dB to 4 dB while the corresponding attenuation for a 2-GHz signal might span 6 dB to 24 dB. This frequency dependent loss causes distortion jitter on the transmitted signal. Each LVCP408 receiver input incorporates an equalizer and compensates for such frequency loss. The SN65LVCP408 equalizer provides 5 dB of frequency gain between 375 MHz and 1.875 GHz, compensating roughly for 20 inches of FR4 material with 8-mil trace width. Distortion jitter improvement is substantial, often providing more than 30-ps jitter reduction. The 5-dB compensation is sufficient for most short backplane traces. For longer trace lengths, it is recommended to enable transmit preemphasis in addition.

SETTING THE PREEMPHASIS LEVEL

The receive equalization compensates for ISI. This reduces jitter and opens the data eye. In order to find the best preemphasis setting for each link, calibration of every link is recommended. Assuming each link consists of a transmitter (with adjustable pre-emphasis such as LVCP408) and the LVCP408 receiver, the following steps are necessary:

- 1. Set the transmitter and receiver to 0-dB preemphasis; record the data eye on the LVCP408 receiver output.
- 2. Increase the transmitter preemphasis until the data eye on the LVCP408 receiver output looks the cleanest.



SLLS842A - JUNE 2009-REVISED JUNE 2010

Ch	nanges from Original (June 2009) to Revision A	Page
•	Added Figures 12 (Figure 11a) and Figure 13 (Figure 11b)	11



10-Dec-2020

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
SN65LVCP408PAPR	ACTIVE	HTQFP	PAP	64	1000	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-40 to 85	LVCP408	Samples
SN65LVCP408PAPT	ACTIVE	HTQFP	PAP	64	250	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-40 to 85	LVCP408	Samples

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

⁽³⁾ MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

⁽⁴⁾ There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

⁽⁵⁾ Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

⁽⁶⁾ Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



PACKAGE OPTION ADDENDUM

10-Dec-2020

PACKAGE MATERIALS INFORMATION

www.ti.com

Texas Instruments

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SN65LVCP408PAPR	HTQFP	PAP	64	1000	330.0	24.4	13.0	13.0	1.5	16.0	24.0	Q2
SN65LVCP408PAPT	HTQFP	PAP	64	250	180.0	24.4	13.0	13.0	1.5	16.0	24.0	Q2

TEXAS INSTRUMENTS

www.ti.com

PACKAGE MATERIALS INFORMATION

14-Feb-2019



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SN65LVCP408PAPR	HTQFP	PAP	64	1000	350.0	350.0	43.0
SN65LVCP408PAPT	HTQFP	PAP	64	250	213.0	191.0	55.0

PAP 64

10 x 10, 0.5 mm pitch

GENERIC PACKAGE VIEW

HTQFP - 1.2 mm max height

QUAD FLATPACK

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.







PowerPAD[™] PLASTIC QUAD FLATPACK



NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at www.ti.com http://www.ti.com.
- E. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.



PAP (S-PQFP-G64)

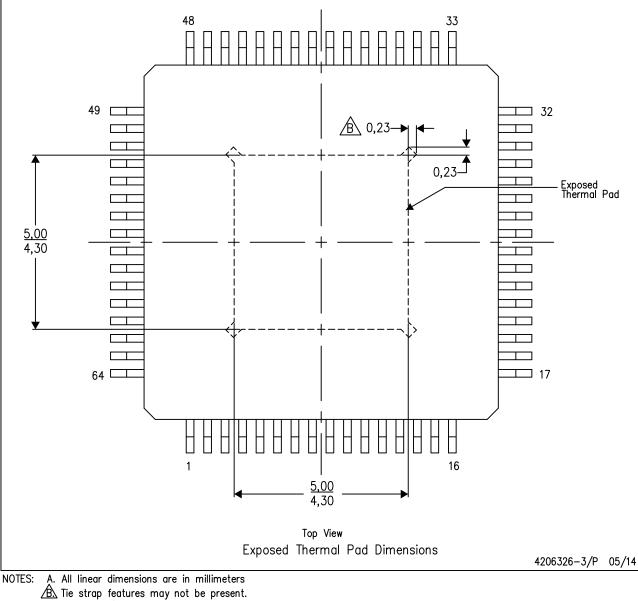
PowerPAD[™] PLASTIC QUAD FLATPACK

THERMAL INFORMATION

This PowerPAD^m package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

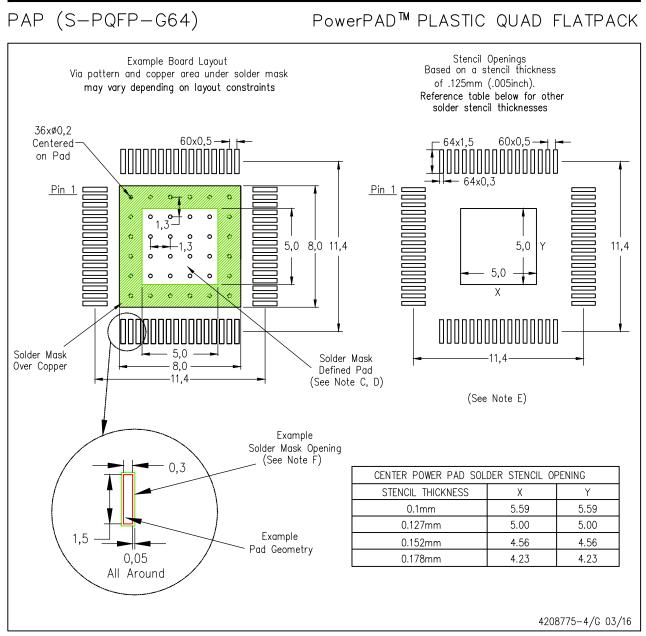
For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.









NOTES:

PowerPAD is a trademark of Texas Instruments

- A. All linear dimensions are in millimeters.B. This drawing is subject to change without notice.
- C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
- D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>. Publication IPC-7351 is recommended for alternate designs.
- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
- F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

TEXAS INSTRUMENTS www.ti.com

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to TI's Terms of Sale (www.ti.com/legal/termsofsale.html) or other applicable terms available either on ti.com or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2020, Texas Instruments Incorporated